



University of Cyprus – MSc Artificial Intelligence

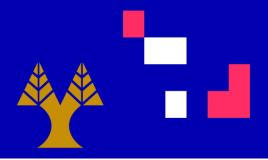
MAI644 - COMPUTER VISION

Lecture 4: Interpolation – Resizing

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Last time

- Pinhole Camera model
 - Aperture
 - Camera Obscura
- Cameras with lenses
 - Thin lens equation
 - Depth of field
 - Field of view
- Digital cameras
 - Bayer filters
 - Debayering









Today's Agenda

- Image basics
 - What is an image addressing pixels
 - Image as a function image coordinates
- Image interpolation
 - Nearest neighbor
 - Bilinear
 - Bicubic
- Image resizing
 - Enlarge
 - Shrink

[material based on Joseph Redmon's course]











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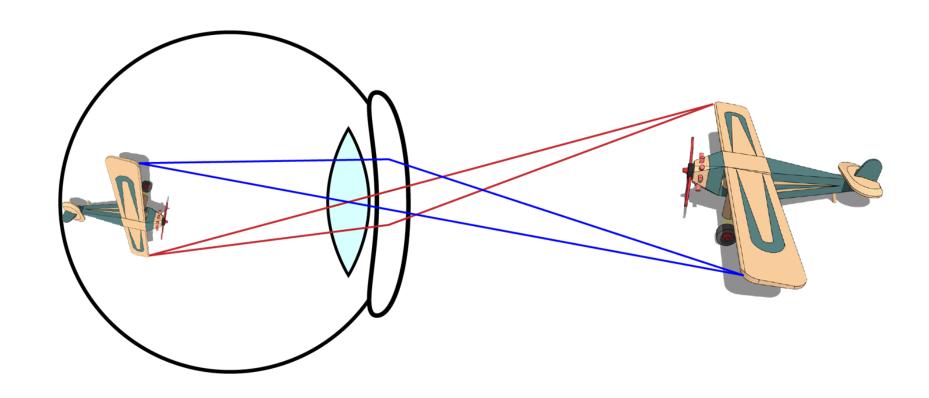








Eyes: projection onto retina





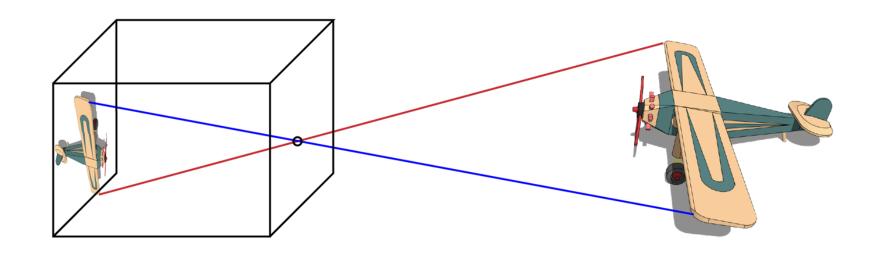








Model: pinhole camera





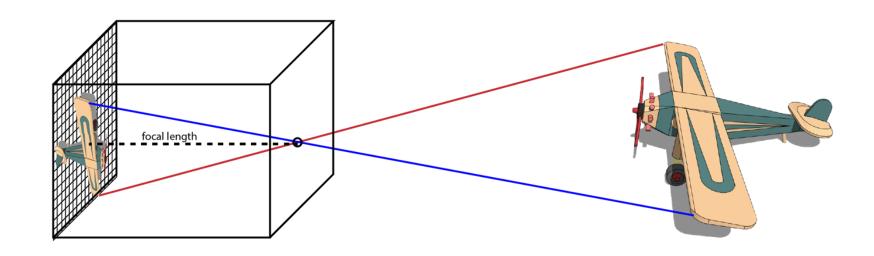








At each point we record incident light





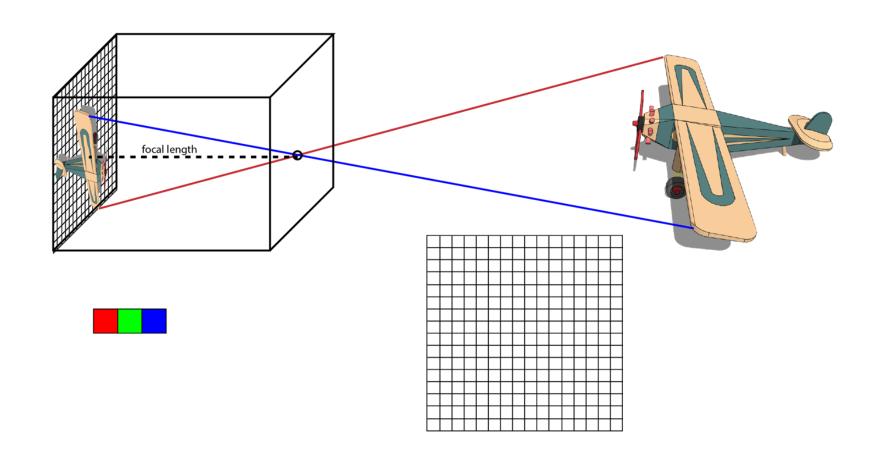








How do we record color?





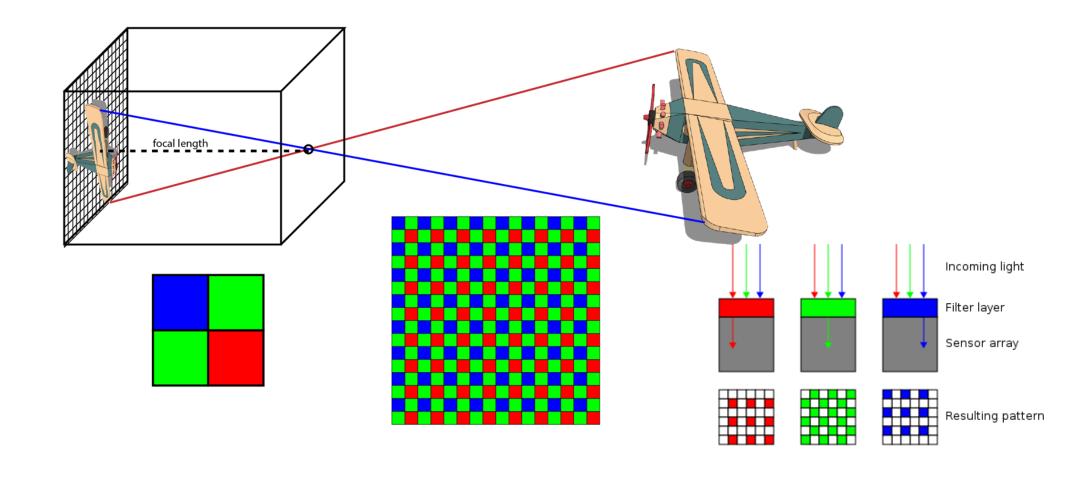








Bayer pattern for CMOS sensors







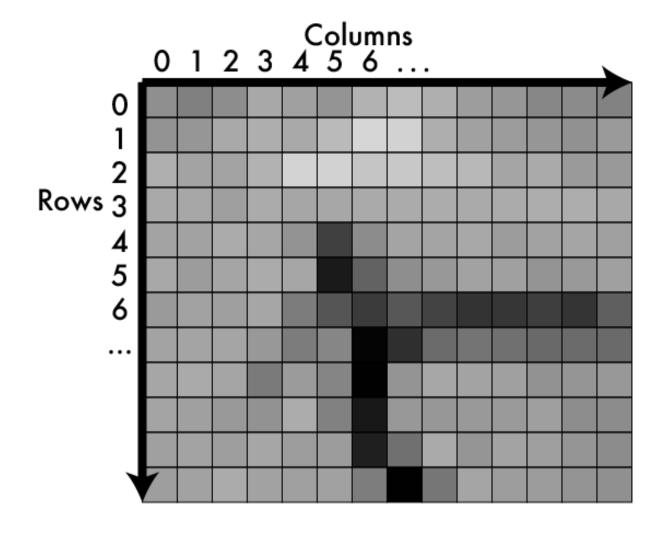








An image is a matrix of light





10









Values in matrix = how much light

	Columns														
		0	1	2	3		5								
	0	100	102	107	102	132	146	136	156	148	122	115	104	105	103
	1	100	102	107	102	132	146	136	156	148	122	115	104	105	103
	2	100	102	107	102	132	146	136	156	148	122	115	104	105	103
Rows	3	100	102	107	102	132	146	136	156	148	122	115	104	105	103
	4	100	102	107	102	132	146	136	156	148	122	115	104	105	103
	5	100	102	107	102	132		60	156	148	122	115	104	105	103
	6	100	102	107	102	132	40	20	50	32	20	20	24	30	62
		100	102	107	102	132	71		156	51	57	57	58	62	58
		100	102	107	102	132	69		156	148	122	115	104	105	103
		100	102	107	102	132	89		156	148	122	115	104	105	103
		100	102	107	102	132	146	13	45	148	122	115	104	105	103
	1	100	102	107	102	132	146	46		42	122	115	104	105	103













Values in matrix = how much light

- Higher = more light
- Lower = less light
- Bounded
 - No light = 0
 - Sensor/device limit = max
 - Typical ranges:
 - [0-255], fit into byte
 - [0-1], floating point
- Called pixels

	Columns 0 1 2 3 4 5 6													
ol	100	102	107	102	132	146	136	156	148	122	115	104	105	103
ĭ	100	102	107	102	132	146	136	156	148	122	115	104	105	103
2	100	102	107	102	132	146	136	156	148	122	115	104	105	103
Rows 3	100	102	107	102	132	146	136	156	148	122	115	104	105	103
4	100	102	107	102	132	146	136	156	148	122	115	104	105	103
5	100	102	107	102	132		60	156	148	122	115	104	105	103
6	100	102	107	102	132	40	20	50	32	20	20	24	30	62
	100	102	107	102	132	71		156	51	57	57	58	62	58
	100	102	107	102	132	69		156	148	122	115	104	105	103
	100	102	107	102	132	89		156	148	122	115	104	105	103
	100	102	107	102	132	146	13	45	148	122	115	104	105	103
1	100	102	107	102	132	146	46		42	122	115	104	105	103





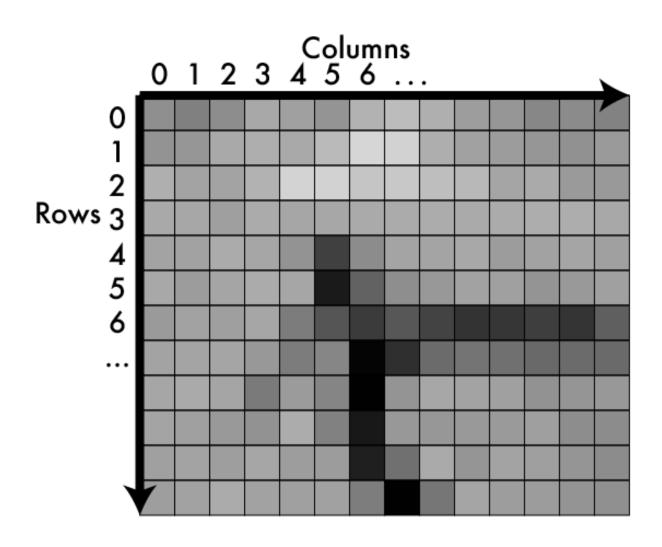






Addressing pixels

- Ways to index:
 - (x,y)
 - Like cartesian coordinates
 - (3,6) is column 3 row 6
 - (r,c)
 - Like matrix notation
 - (3,6) is row 3 column 6
- We use (x,y)
 - Arbitrary
 - Only thing that matters is consistency





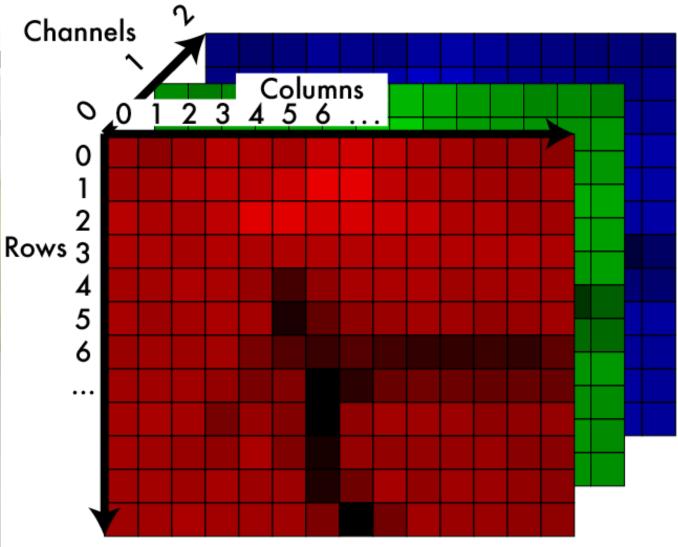






Color image: 3d tensor in colorspace











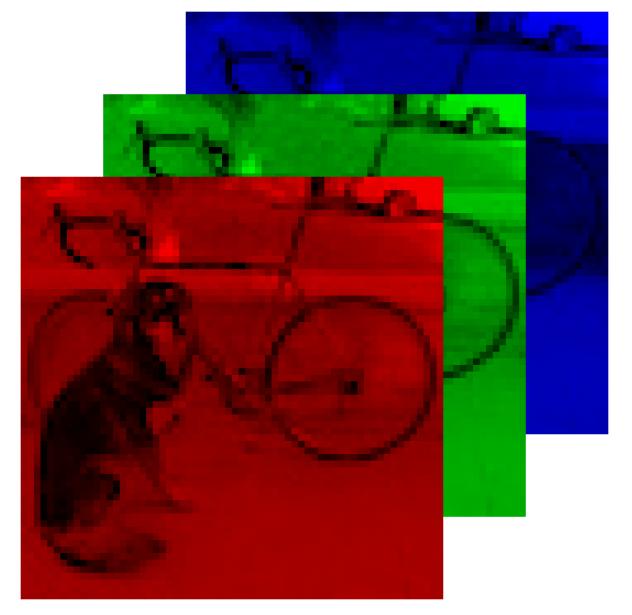




RGB information in separate "channels"

Remember: we can match "real" colors using a mix of primaries.

Each channel encodes one primary. Adding the light produced from each primary mimics the original color.





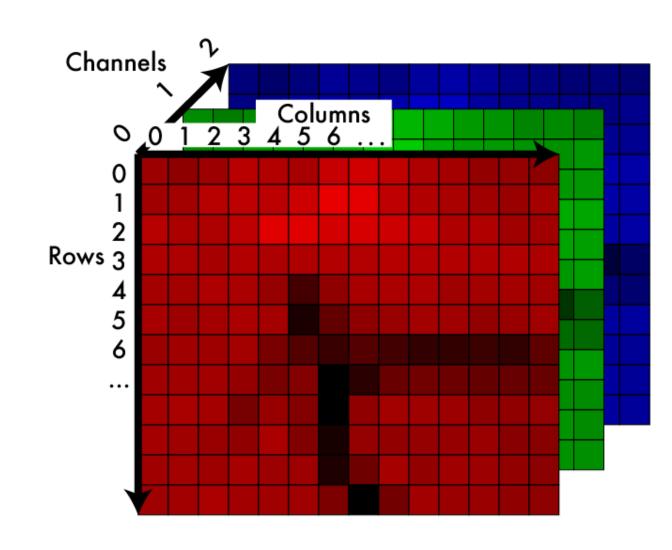






Addressing pixels

- We use (x,y,c)
 - (1,2,0):
 - column 1, row 2, channel 0
- Still doesn't matter, just be consistent
- Also for size:
 - 1920 x 1080 x 3 image:
 - 1920 px wide
 - 1080 px tall
 - 3 channels













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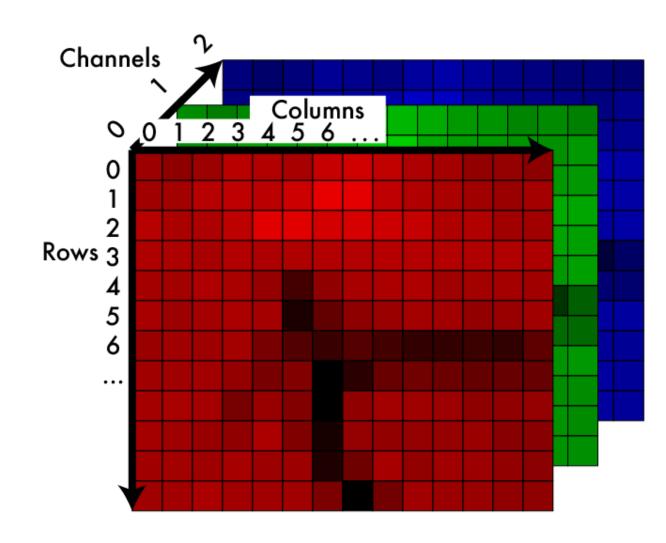
An image is like a function

An image is a mapping from indices to pixel value:

- $lm: lx lx l \rightarrow R$

We may want to pass in non-integers:

- $Im': R \times R \times I -> R$



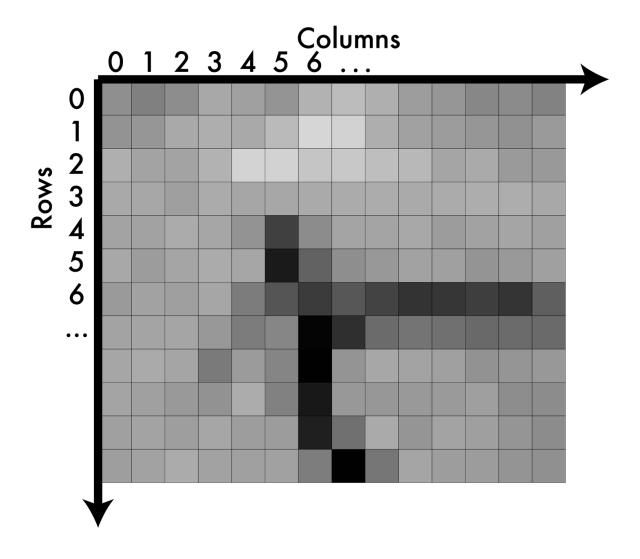












integer pixels



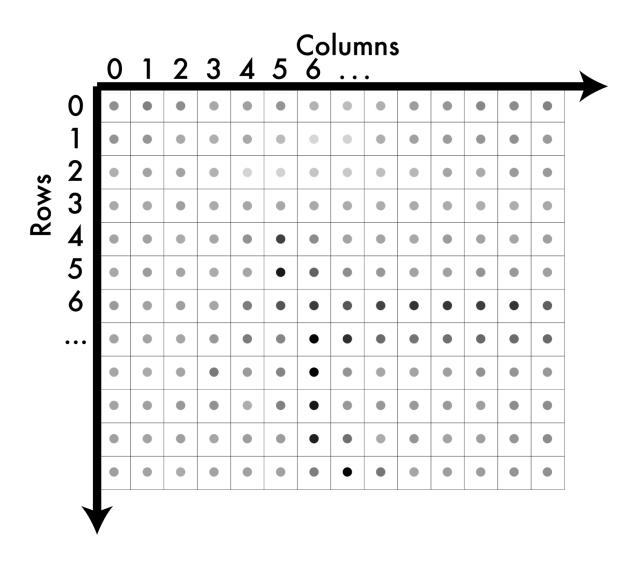












We can think of their values as being at the centers.

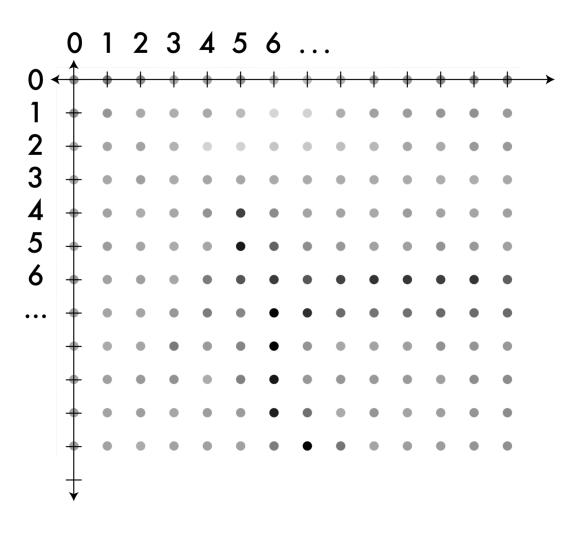












Now we can move to a real coordinate system.

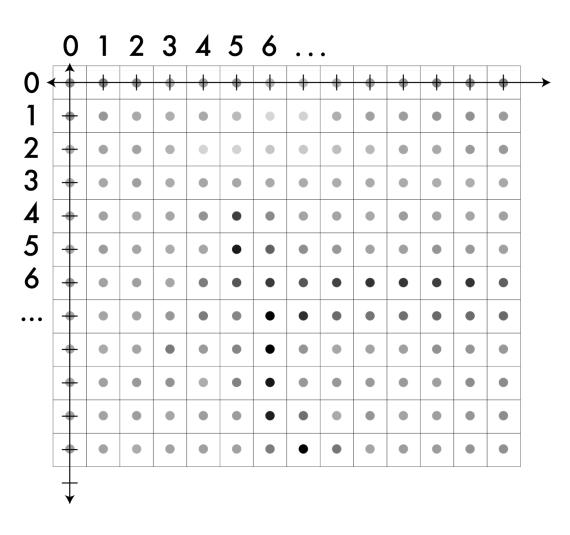












On the image

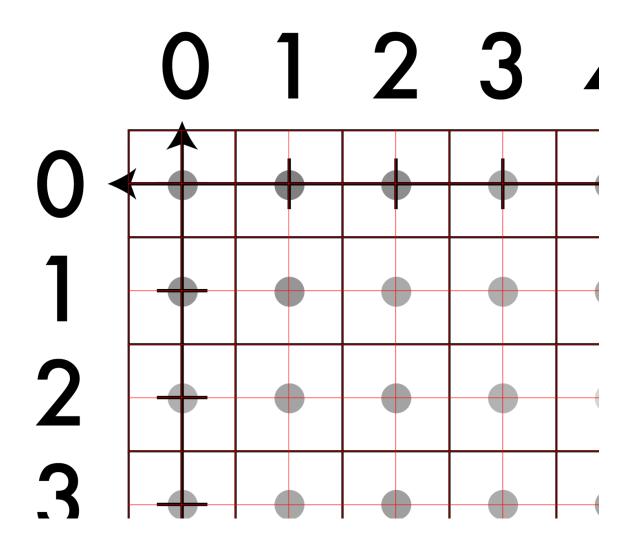








So, the value of the pixel (x,y) is now centered at (x,y).







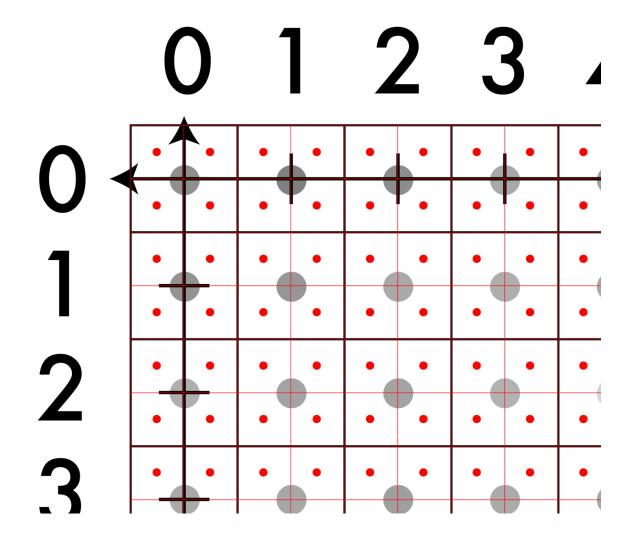
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under GA nr. INEA/CÉF/ICT/A2020/2267423





But there are other real-valued points.

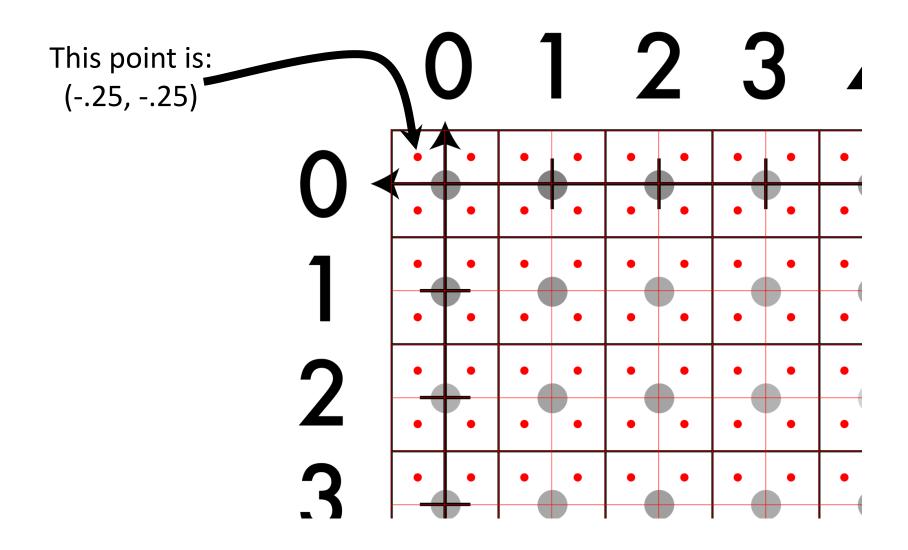






















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Interpolation

How do we find out the VALUE of a non-integer point, when the image only comes with integer points, i.e. (25,45,3).

Two simple ideas:

- 1. Nearest-Neighbor Interpolation
- 2. Bilinear Interpolation













Nearest neighbor: what it sounds like

f(x,y,z) = Im(round(x), round(y), z)

- Looks blocky
- Note: z is still int













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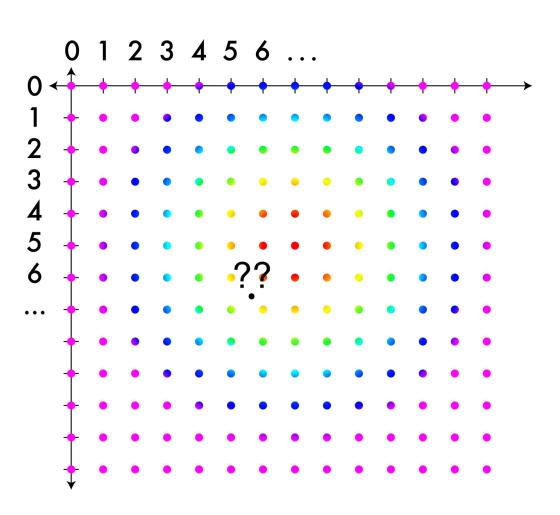








This time find the closest pixels in a box



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No 2020-EU-IA-0087, co-financed by the EU CEF Telecom







This time find the closest pixels in a box











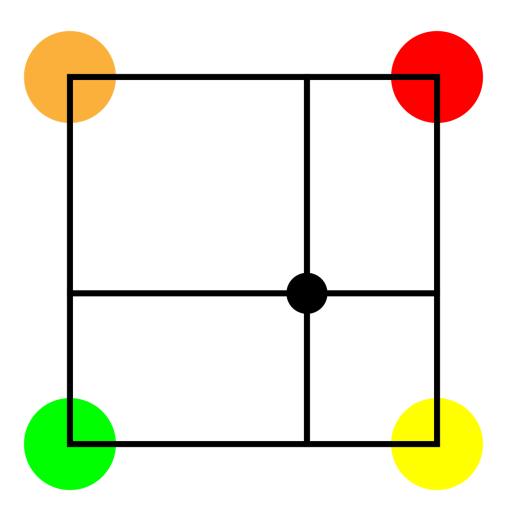








This time find the closest pixels in a box











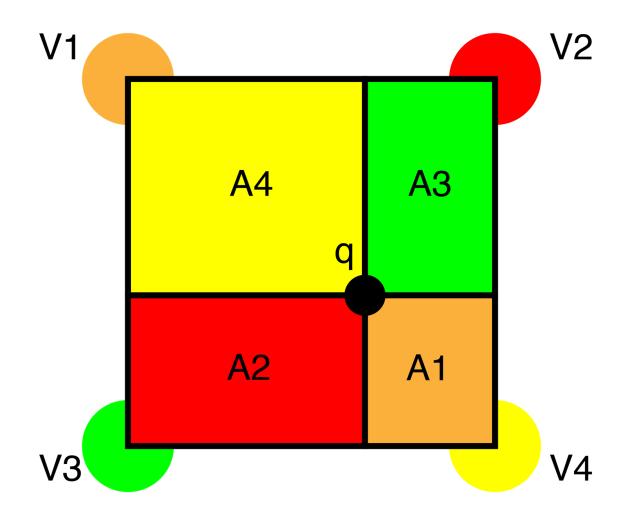
This time find the closest pixels in a box

Weighted sum based on area of opposite rectangle

$$q = V1*A1 + V2*A2 + V3*A3 + V4*A4$$

Need to normalize!

Or do we?











$$q = V1*A1 + V2*A2 + V3*A3 + V4*A4$$

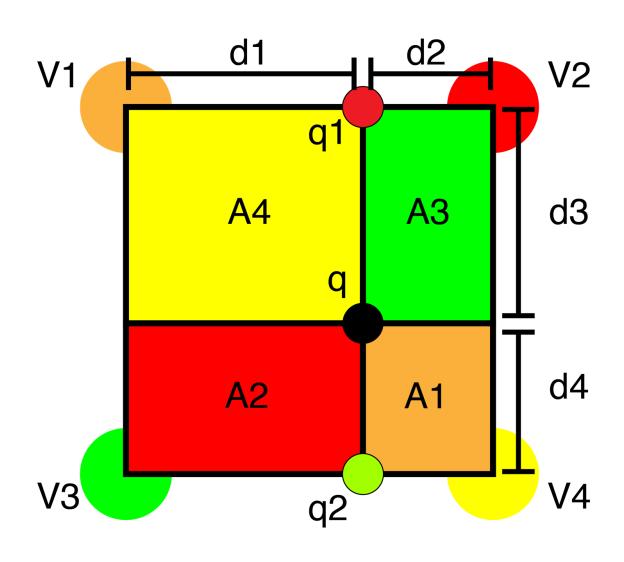
A1 = d2*d4

A2 = d1*d4

A3 = d2*d3

A4 = d1*d3

$$=> q = V1*d2*d4 + V2*d1*d4 + V3*d2*d3 + V4*d1*d3$$









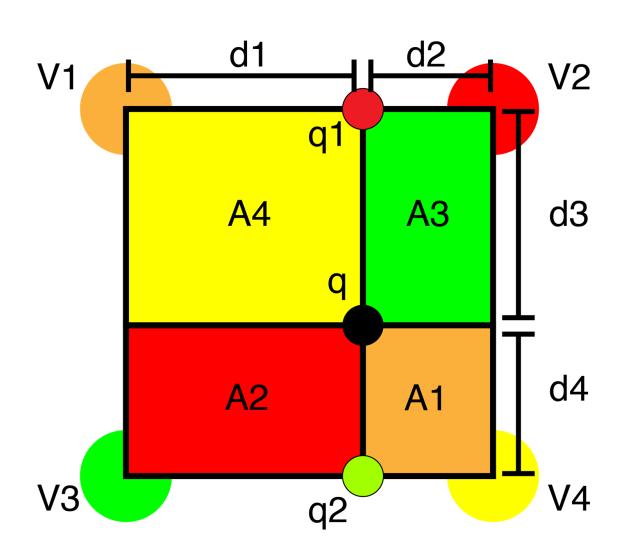


Alternatively, linear interpolation of linear interpolates

$$q1 = V1*d2 + V2*d1$$

$$q2 = V3*d2 + V4*d1$$

$$q = q1*d4 + q2*d3$$











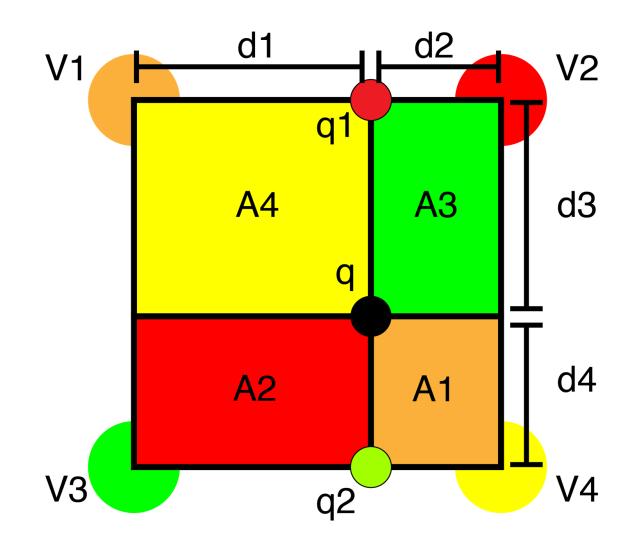
$$q1 = V1*d2 + V2*d1$$

$$q2 = V3*d2 + V4*d1$$

$$q = q1*d4 + q2*d3$$

Equivalent:

q = q1*d4 + q2*d3











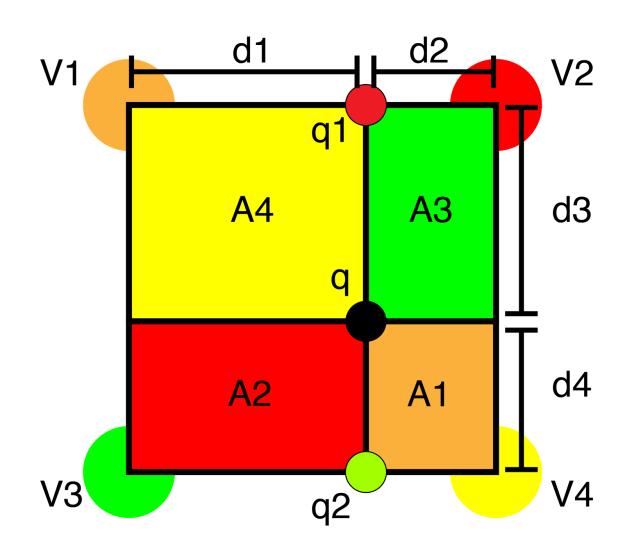
$$q1 = V1*d2 + V2*d1$$

$$q2 = V3*d2 + V4*d1$$

$$q = q1*d4 + q2*d3$$

Equivalent:

```
q = q1*d4 + q2*d3
q = (V1*d2 + V2*d1)*d4 + (V3*d2 + V4*d1)*d3 (subst)
```











$$q1 = V1*d2 + V2*d1$$

$$q2 = V3*d2 + V4*d1$$

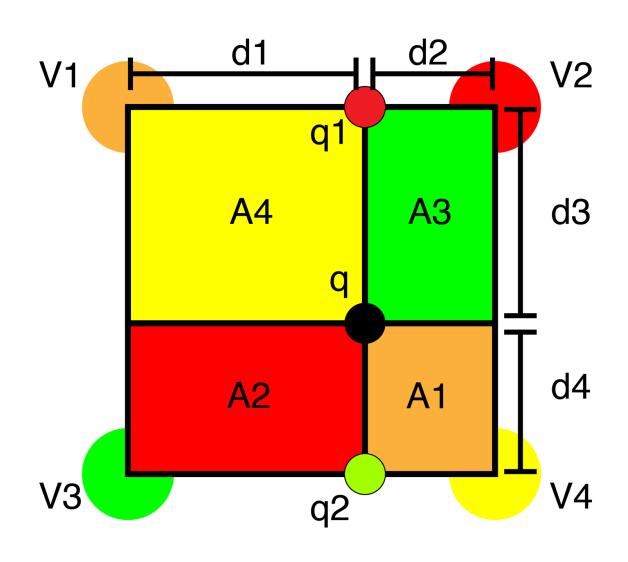
$$q = q1*d4 + q2*d3$$

Equivalent:

```
q = q1*d4 + q2*d3
```

q = (V1*d2 + V2*d1)*d4 + (V3*d2 + V4*d1)*d3 (subst)

q = V1*d2*d4 + V2*d1*d4 + V3*d2*d3 + V4*d1*d3 (distribution)













$$q1 = V1*d2 + V2*d1$$

$$q2 = V3*d2 + V4*d1$$

$$q = q1*d4 + q2*d3$$

Equivalent:

q = q1*d4 + q2*d3

q = (V1*d2 + V2*d1)*d4 + (V3*d2 + V4*d1)*d3 (subst)

q = V1*d2*d4 + V2*d1*d4 + V3*d2*d3 + V4*d1*d3 (distribution)

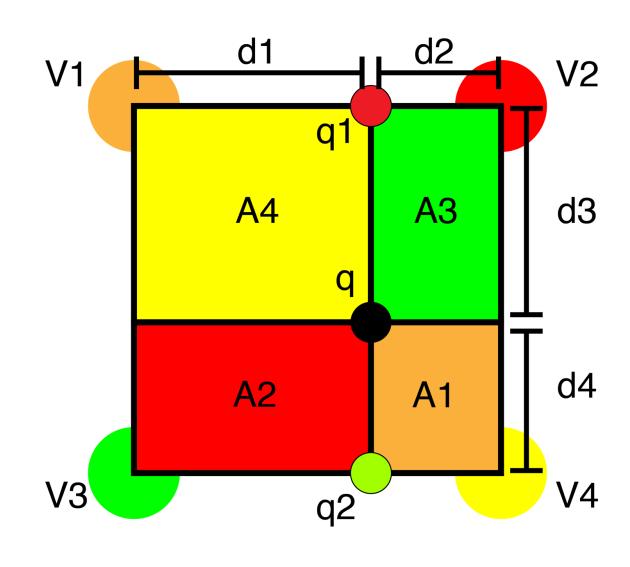
Recall:

A1 = d2*d4

A2 = d1*d4

A3 = d2*d3

A4 = d1*d3













$$q1 = V1*d2 + V2*d1$$

$$q2 = V3*d2 + V4*d1$$

$$q = q1*d4 + q2*d3$$

Equivalent:

q = q1*d4 + q2*d3

q = (V1*d2 + V2*d1)*d4 + (V3*d2 + V4*d1)*d3 (subst)

q = V1*d2*d4 + V2*d1*d4 + V3*d2*d3 + V4*d1*d3 (distribution)

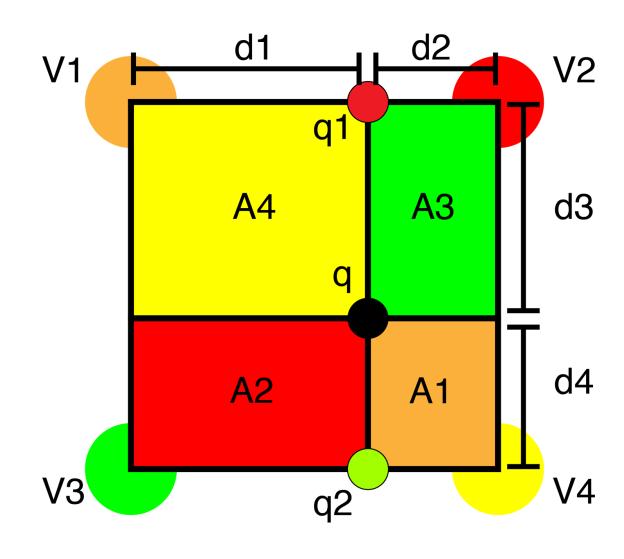
Recall:

A1 = d2*d4

A2 = d1*d4

A3 = d2*d3A4 = d1*d3

q = V1*A1 + V2*A2 + V3*A3 + V4*A4



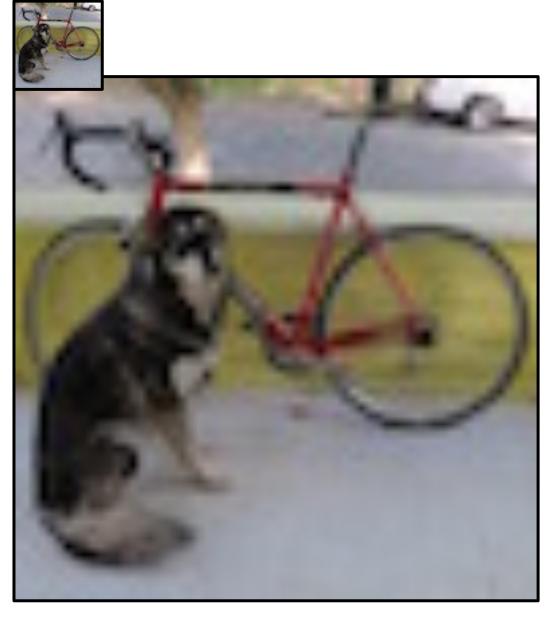








- Smoother than NN
- More complex
 - 4 lookups
 - Some math
- Often the right tradeoff of speed vs final result













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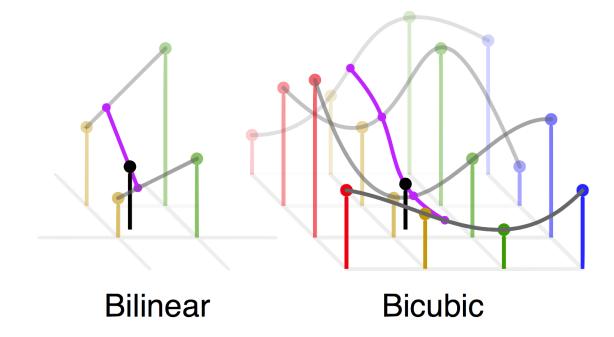






Bicubic sampling: more complex, maybe better?

- A cubic interpolation of 4 cubic interpolations
- Smoother than bilinear, no "star"
- 16 nearest neighbors
- Fit 3rd order poly:
 - $f(x) = a + bx + cx^2 + dx^3$
- Interpolate along axis
- Fit another poly to interpolated values





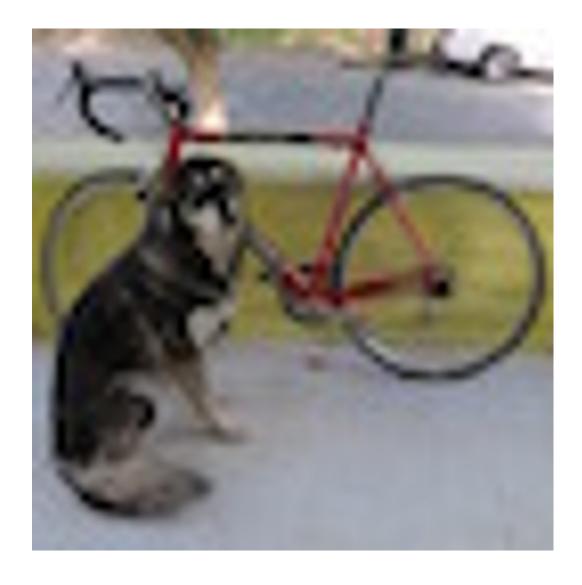


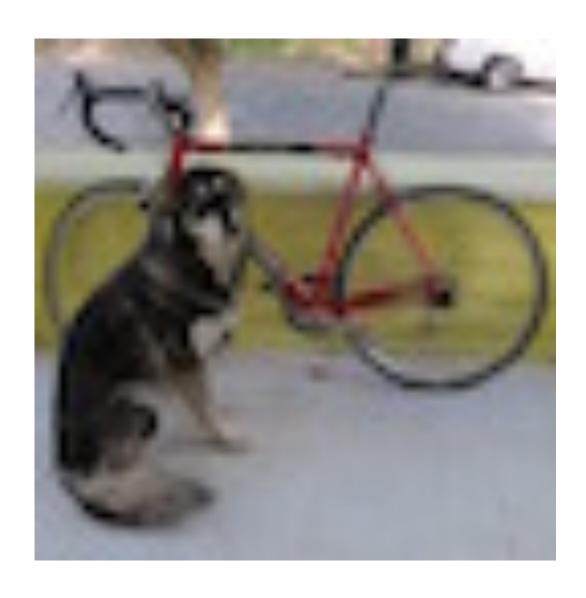






Bicubic vs bilinear





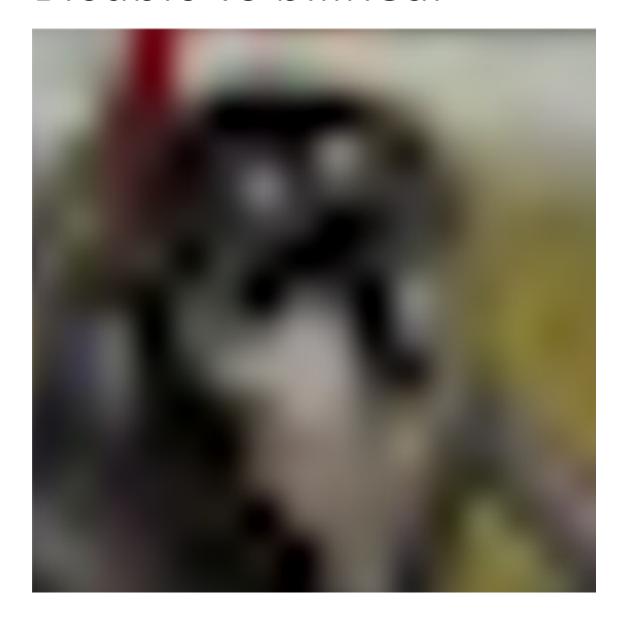


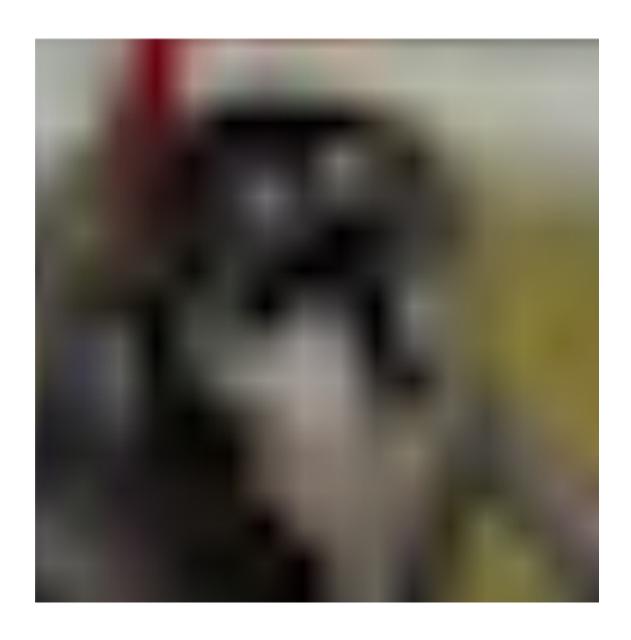






Bicubic vs bilinear







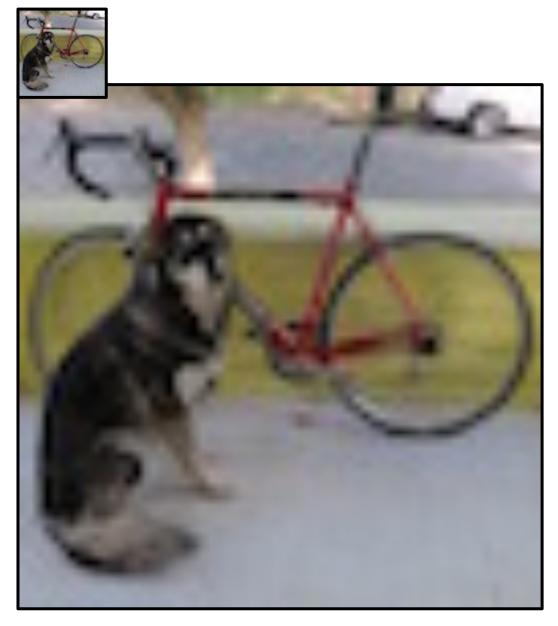






Resize algorithm:

- For each pixel in new image:
 - Map to old im coordinates
 - Interpolate value
 - Set new value in image













So what is this interpolation useful for?







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Image resizing!

Say we want to increase the size of an image...

This is a beautiful image of a sunset... it's just very small...

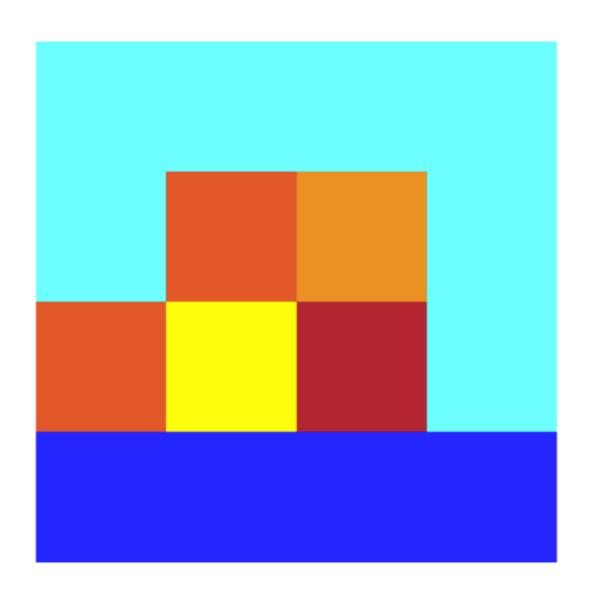








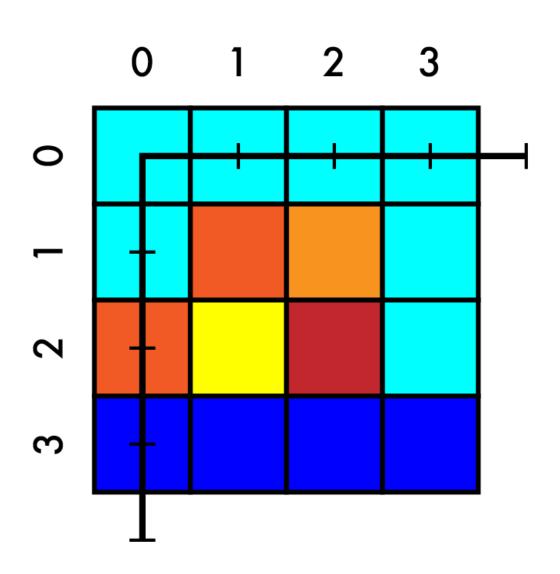


Image resizing!

Say we want to increase the size of an image...

This is a beautiful image of a sunset... it's just very small...

Say we want to increase size 4x4 - 7x7



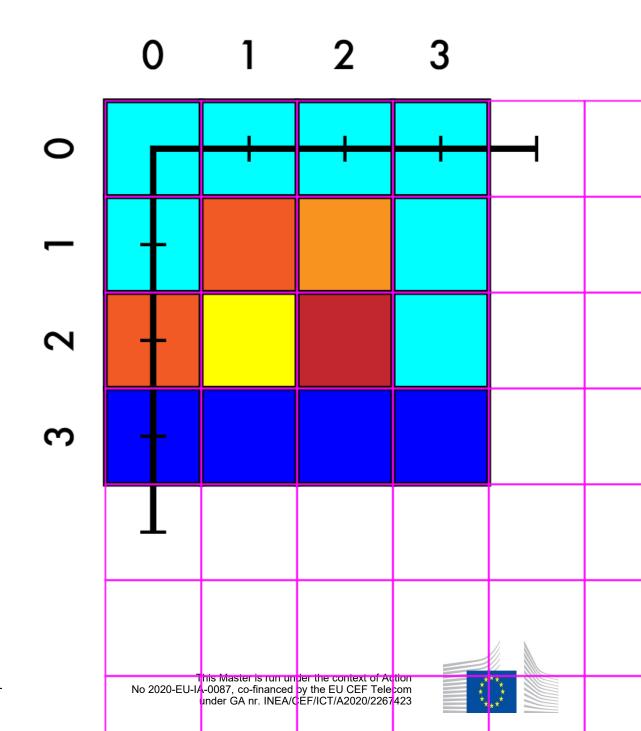








Create our new image

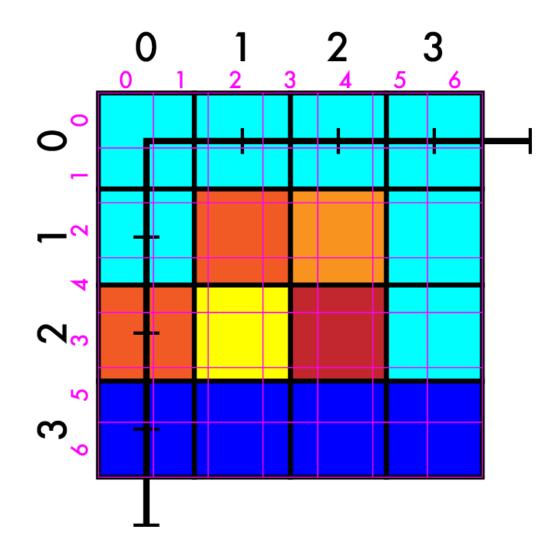








- Create our new image
- Match up coordinates





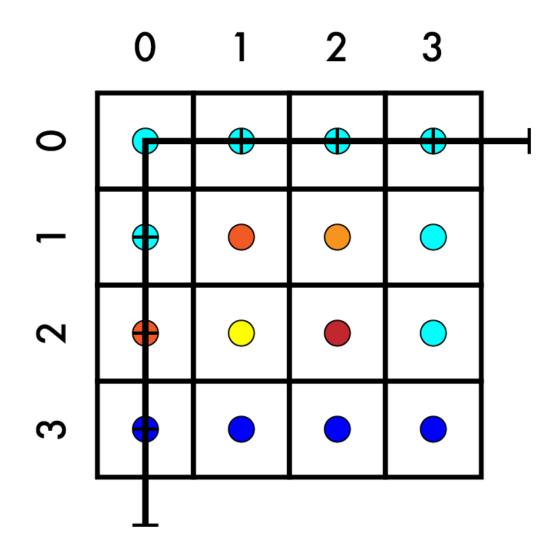








- Create our new image
- Match up coordinates





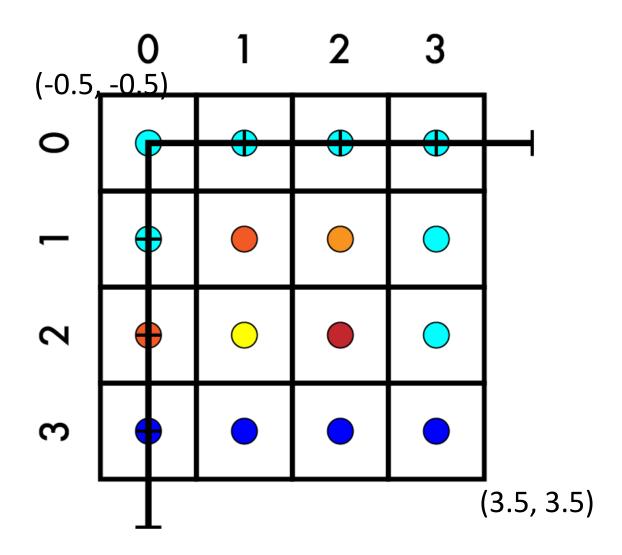








- Create our new image
- Match up coordinates





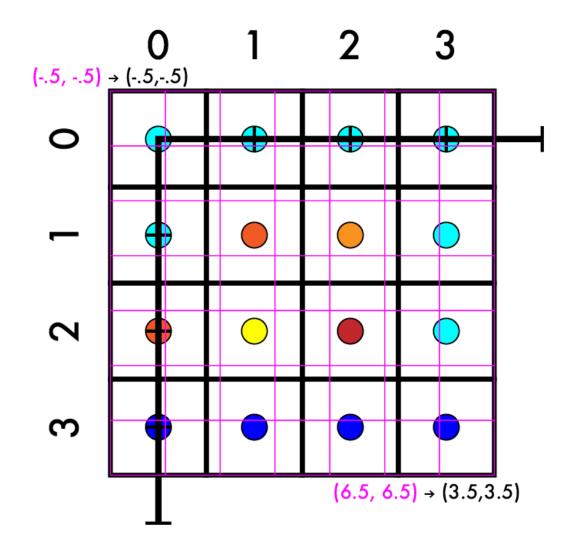








- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5





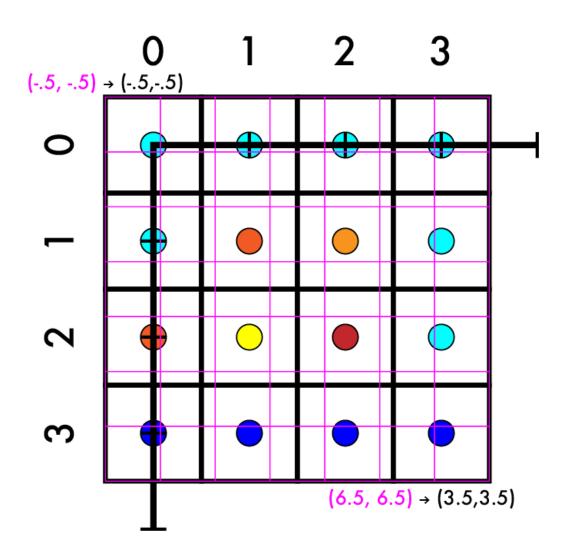






- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5

$$- a*7 = 4$$



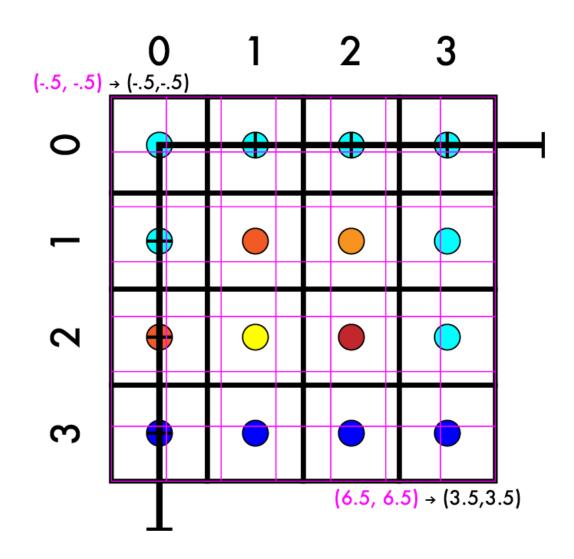








- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5
 - -a*7=4
 - a = 4/7



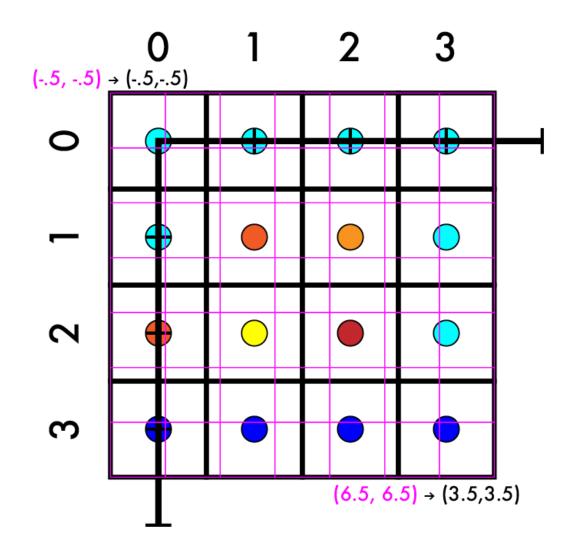








- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5
 - a = 4/7



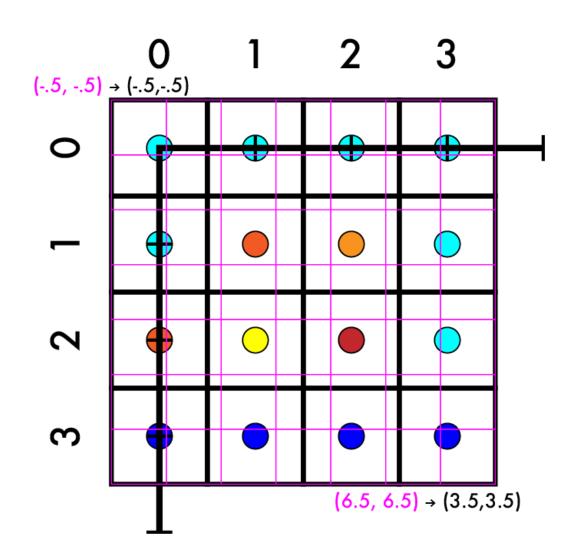








- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5
 - a = 4/7
 - $-a^*-.5+b=-.5$





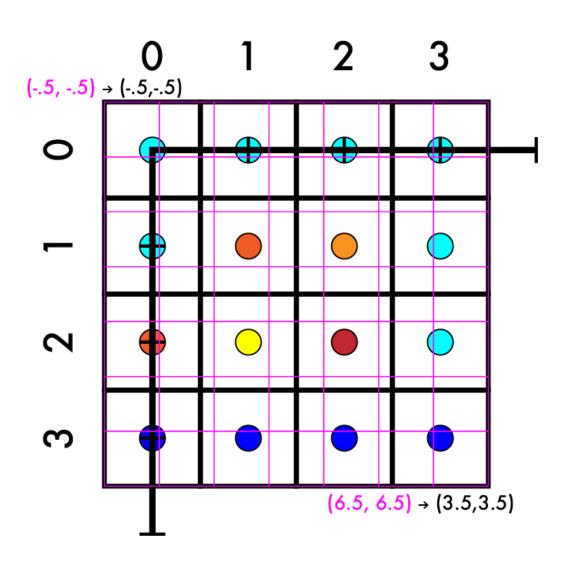








- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5
 - a = 4/7
 - a^* -.5 + b = -.5
 - -4/7*-1/2 + b = -1/2



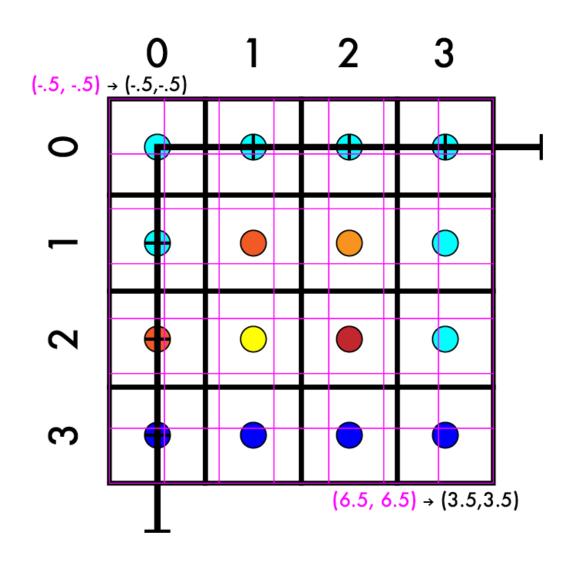








- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - a^* -.5 + b = -.5
 - a*6.5 + b = 3.5
 - a = 4/7
 - $-a^*-.5+b=-.5$
 - -4/7*-1/2 + b = -1/2
 - -4/14 + b = -7/14



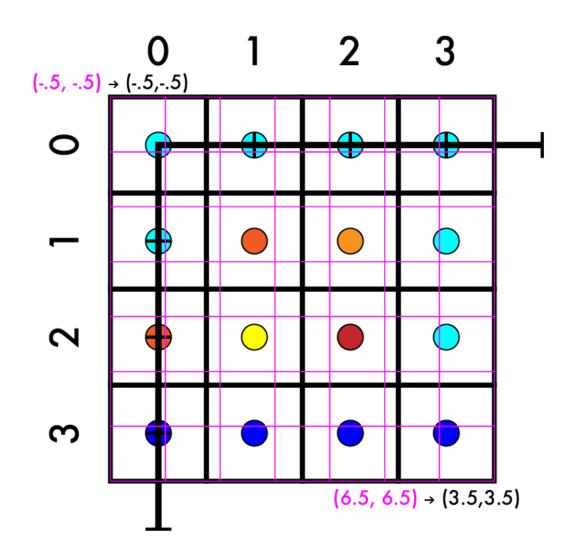








- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5
 - a = 4/7
 - $-a^*-.5+b=-.5$
 - -4/7*-1/2 + b = -1/2
 - -4/14 + b = -7/14
 - b = -3/14



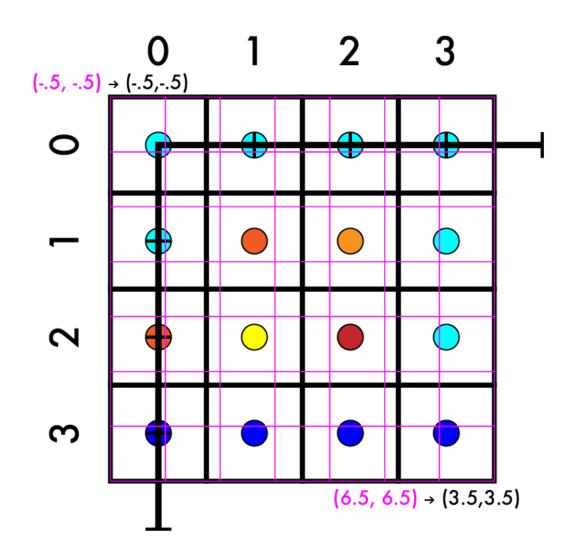








- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - -a*6.5 + b = 3.5
 - a = 4/7
 - b = -3/14





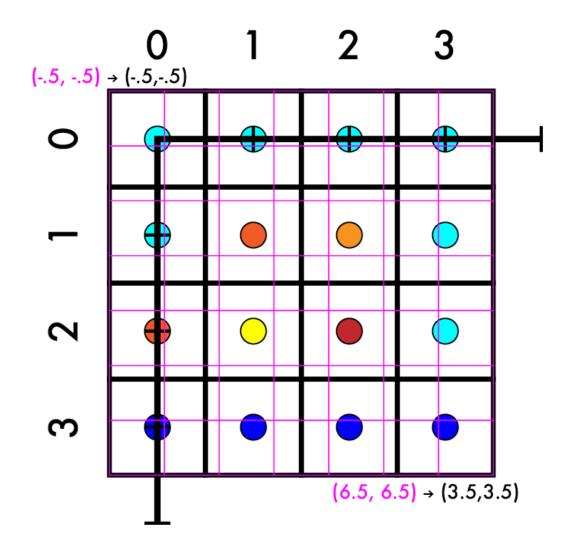








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y





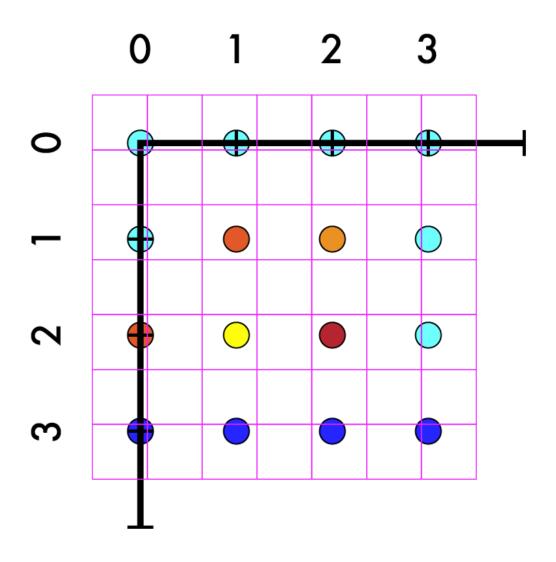








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y





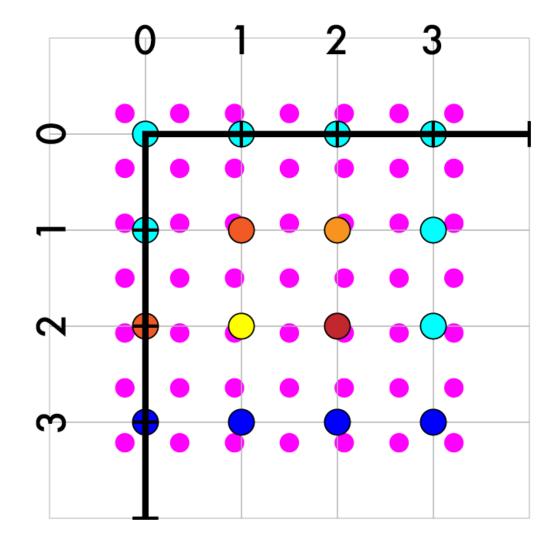








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts





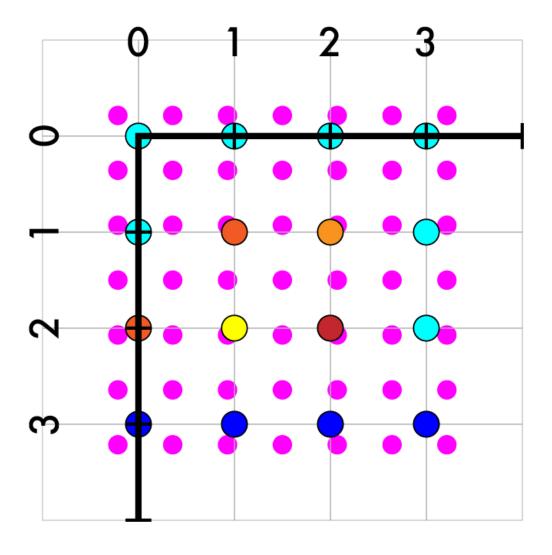








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords





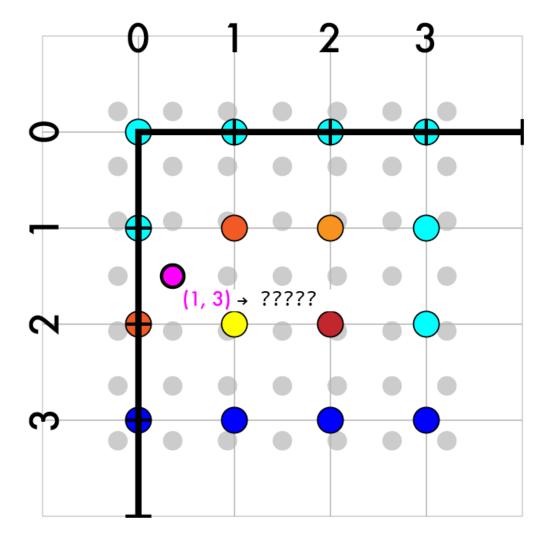
67







- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3)



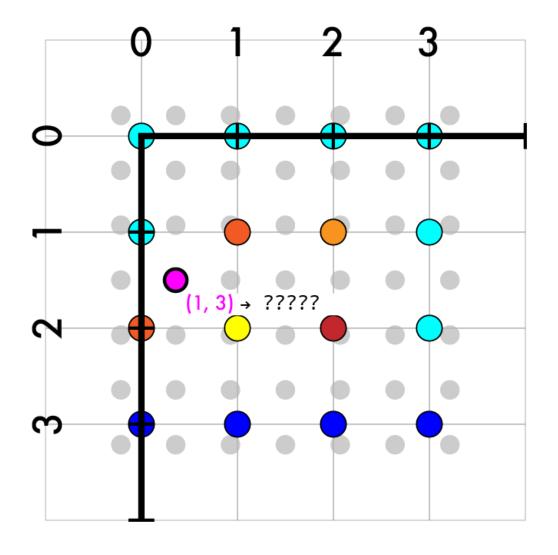








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3)
 - 4/7*1 3/14
 - **-** 4/7*3 3/14







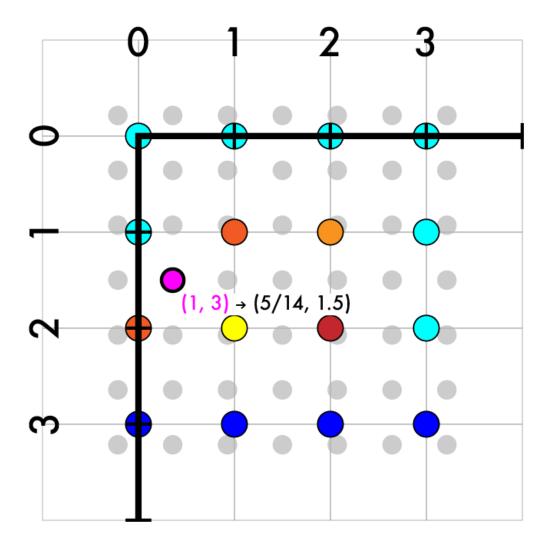






- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords

 - **-** 4/7*1 3/14
 - 4/7*3 3/14
 - (5/14, 21/14)





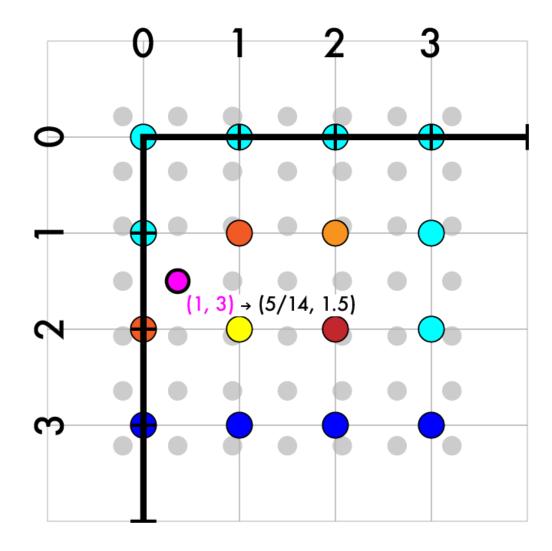






Resize $4x4 \rightarrow 7x7$

- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - $(1, 3) \rightarrow (5/14, 21/14)$



This Master is run under the context of Action

under GA nr. INEA/CÉF/ICT/A2020/2267423



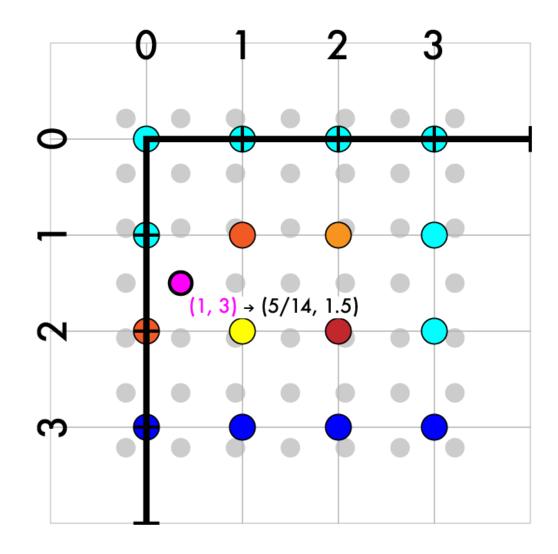








- Create our new image
- Match up coordinates
 - -4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values





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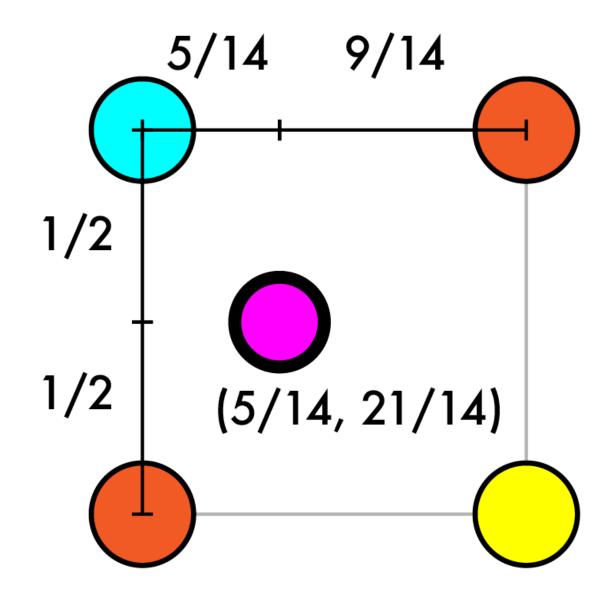








- Create our new image
- Match up coordinates
 - -4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values





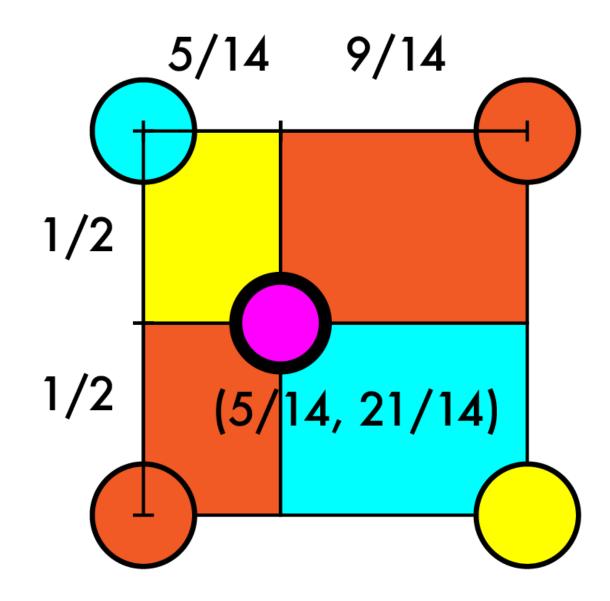








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - Size of opposite rects



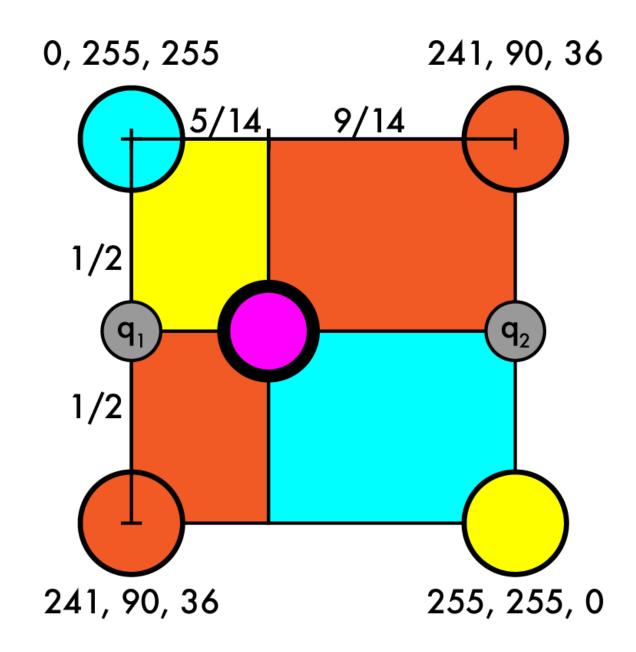








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - $(1, 3) \rightarrow (5/14, 21/14)$
 - Interpolate old values
 - Size of opposite rects
 - OR find q1 and q2, then interpolate between them



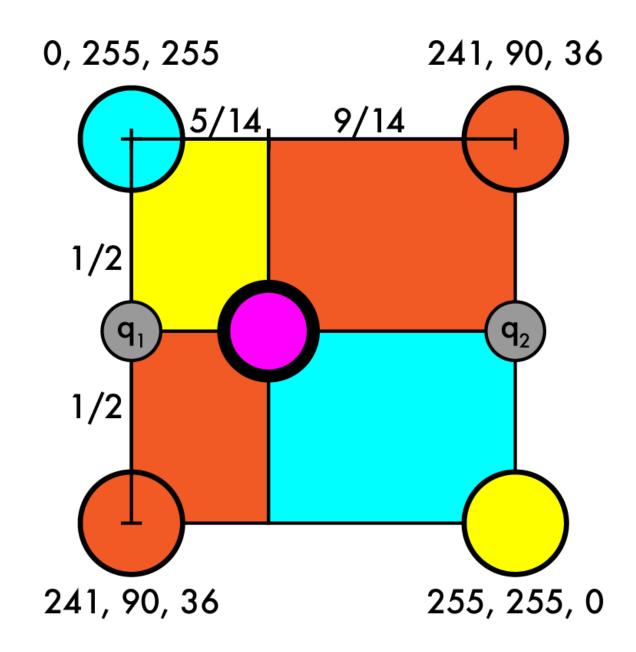








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - q1 = r1, g1, b1
 - r1 = .5*0 + .5*241
 - g1 = .5*255 + .5*90
 - b1 = .5*255 + .5*36

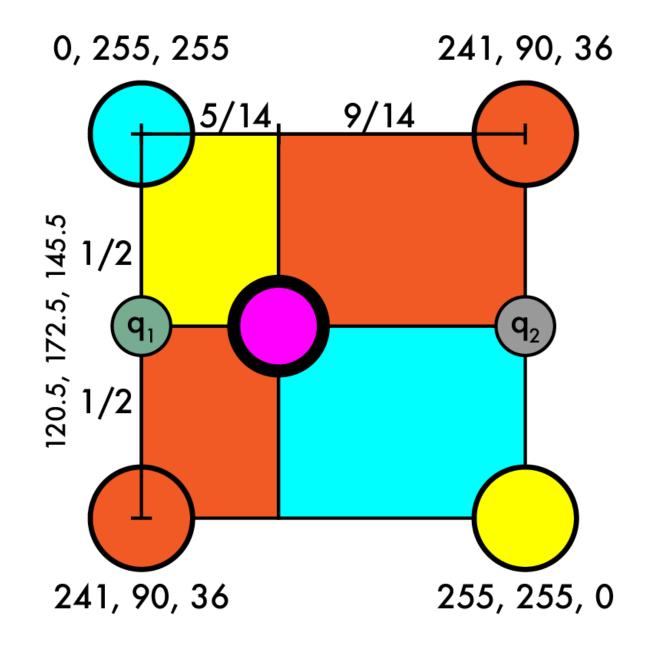








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - q1 = (120.5, 172.5, 145.5)
 - -q2 = r2, g2, b2

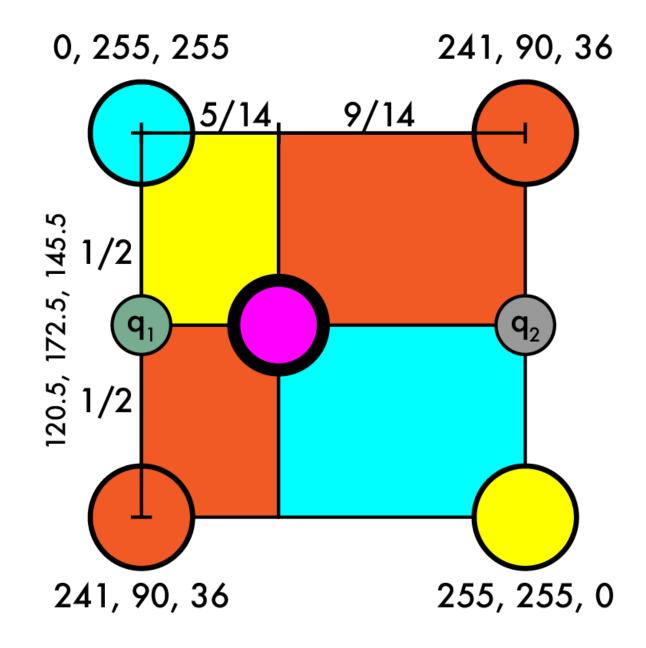








- Create our new image
- Match up coordinates
 - -4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - q1 = (120.5, 172.5, 145.5)
 - -q2 = r2, g2, b2
 - r2 = .5*241 + .5*255
 - g2 = .5*90 + .5*255
 - b2 = .5*36 + .5*0

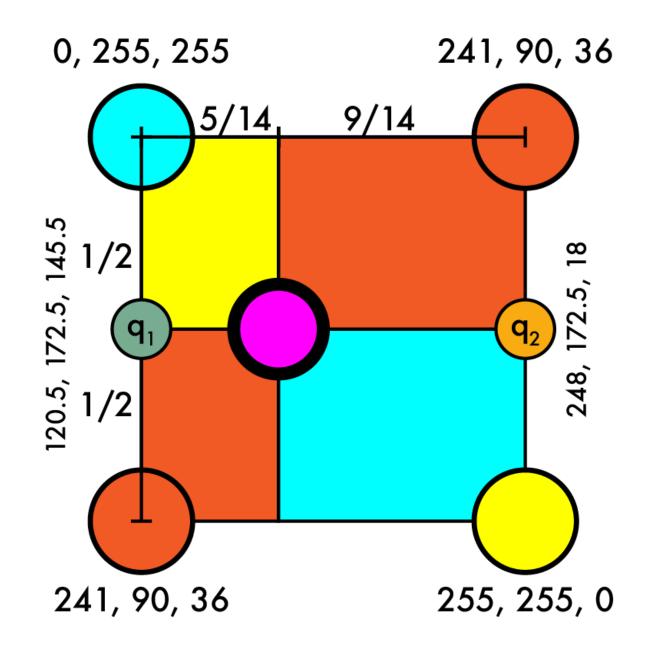








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - $(1, 3) \rightarrow (5/14, 21/14)$
 - Interpolate old values
 - q1 = (120.5, 172.5, 145.5)
 - -q2 = (248, 172.5, 18)

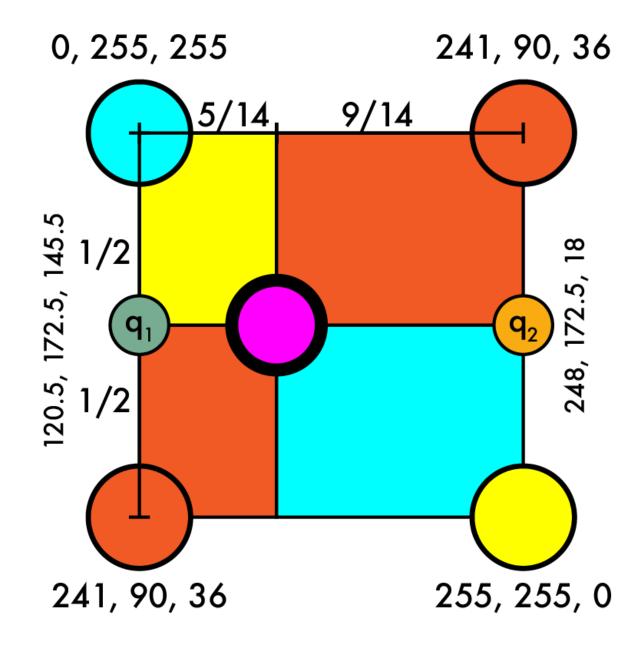








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - q1 = (120.5, 172.5, 145.5)
 - q2 = (248, 172.5, 18)
 - q = r, g, b
 - q = 9/14*q1 + 5/14*q2

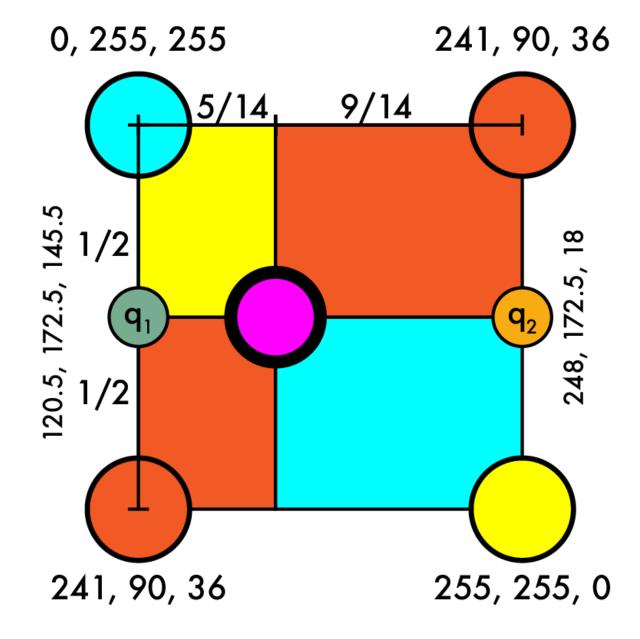








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - q1 = (120.5, 172.5, 145.5)
 - q2 = (248, 172.5, 18)
 - q = r, g, b
 - q = 9/14*q1 + 5/14*q2
 - r = 9/14*120.5 + 5/14*248
 - g = 9/14*172.5 + 5/14*172.5
 - b = 9/14*145.5 + 5/14*18



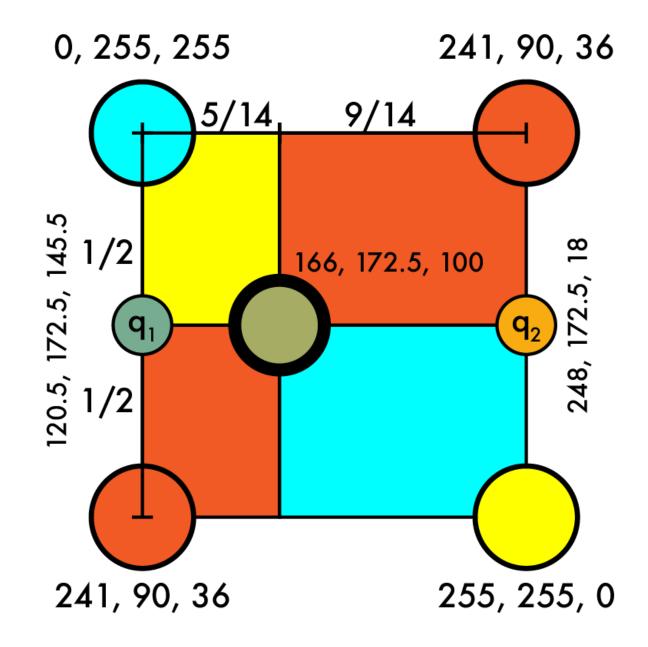








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - q1 = (120.5, 172.5, 145.5)
 - -q2 = (248, 172.5, 18)
 - -q = (166, 172.5, 100)





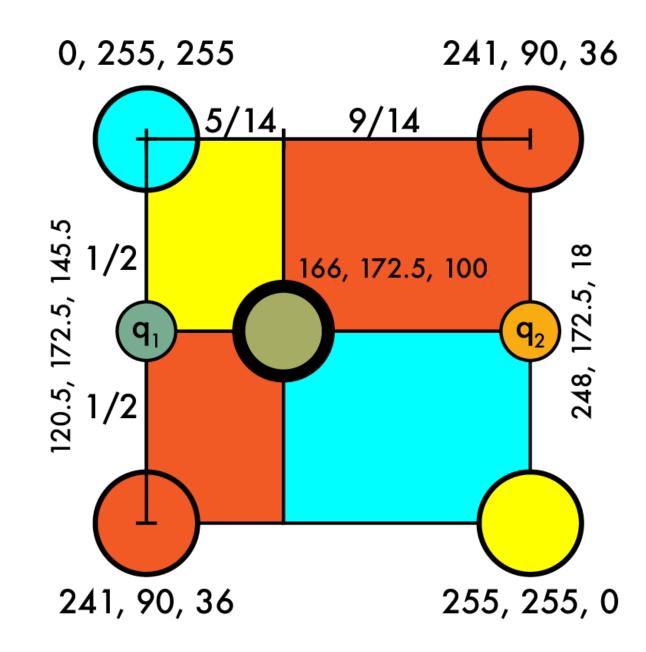








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - $(1, 3) \rightarrow (5/14, 21/14)$
 - Interpolate old values
 - q = (166, 172.5, 100)





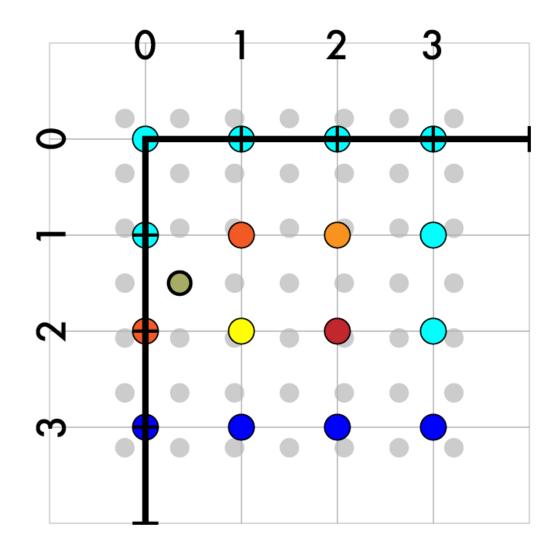








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - $(1, 3) \rightarrow (5/14, 21/14)$
 - Interpolate old values
 - q = (166, 172.5, 100)





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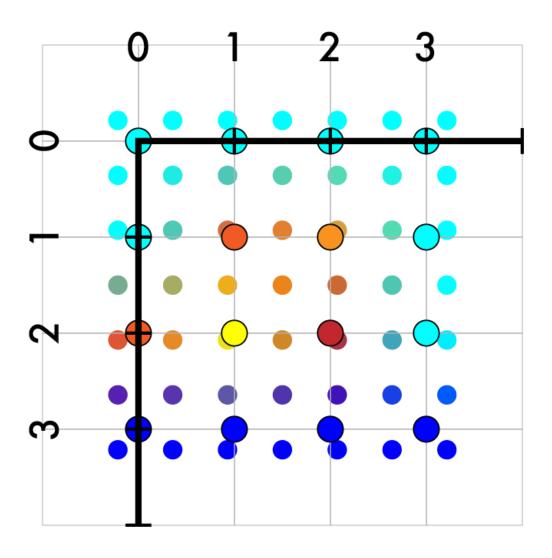








- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - $(1, 3) \rightarrow (5/14, 21/14)$
 - Interpolate old values
 - q = (166, 172.5, 100)
- Fill in the rest





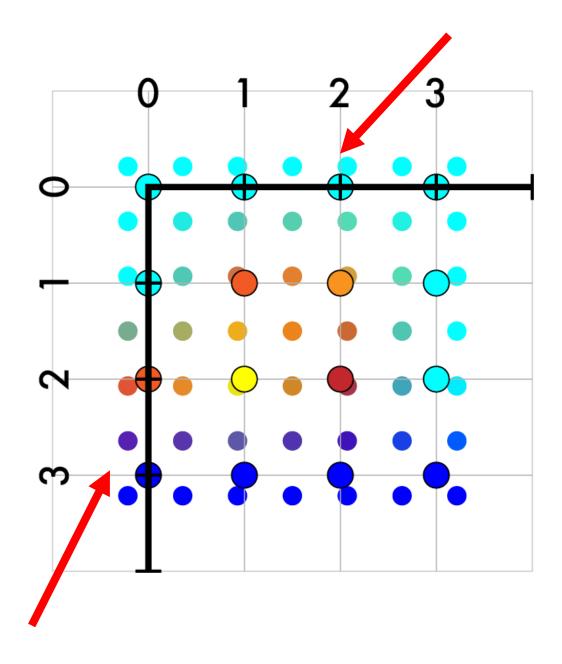






Resize $4x4 \rightarrow 7x7$

- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - $(1, 3) \rightarrow (5/14, 21/14)$
 - Interpolate old values
 - q = (166, 172.5, 100)
- Fill in the rest
 - On outer edges use padding!



This Master is run under the context of Action

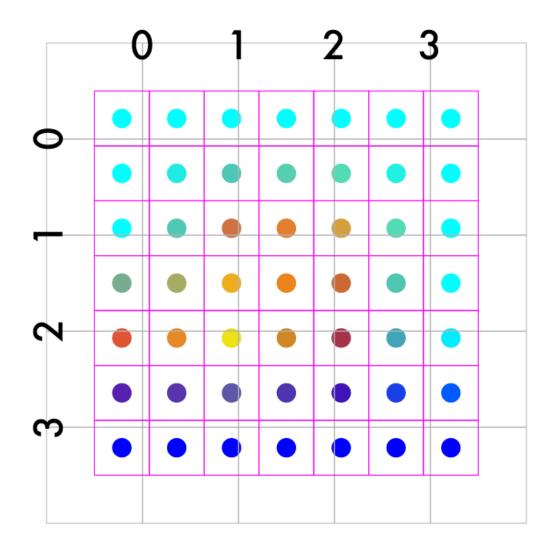
under GA nr. INEA/CÉF/ICT/A2020/2267423







- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - q = (166, 172.5, 100)
- Fill in the rest





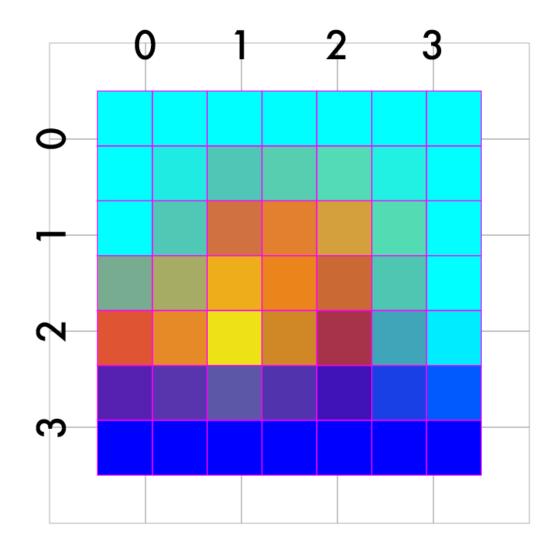








- Create our new image
- Match up coordinates
 - -4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - $(1, 3) \rightarrow (5/14, 21/14)$
 - Interpolate old values
 - q = (166, 172.5, 100)
- Fill in the rest

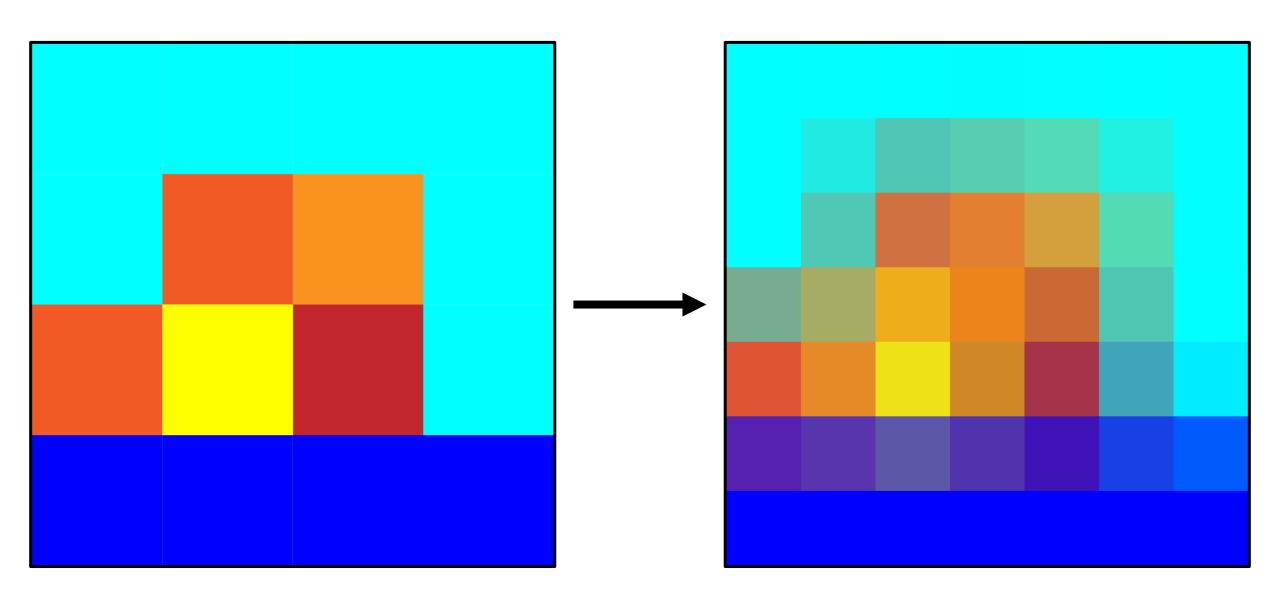








We did it!



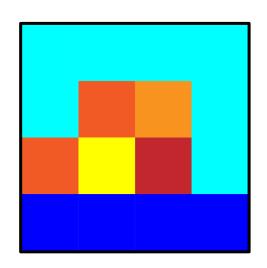


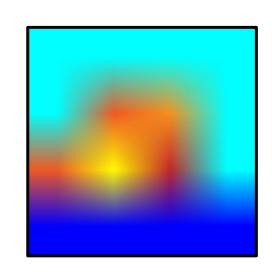




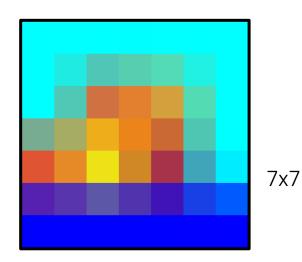


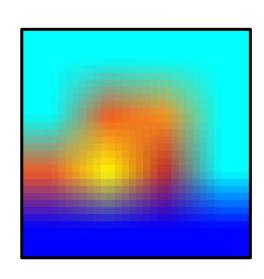
Different scales





256x256





32x32

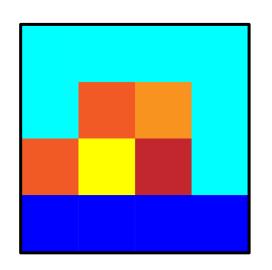


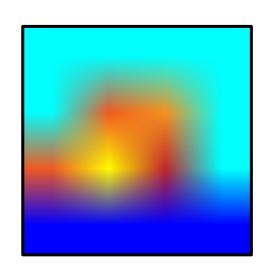


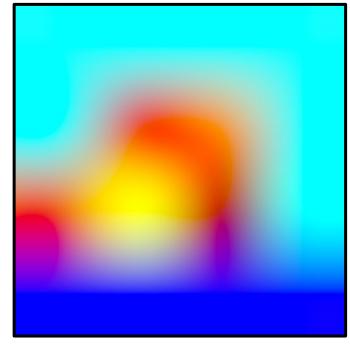




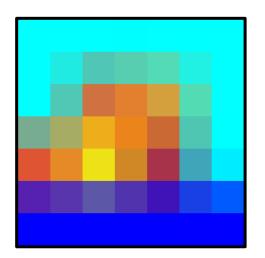
Different methods

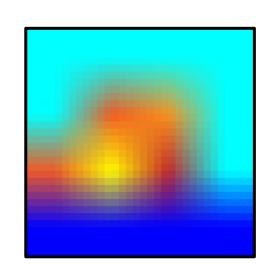


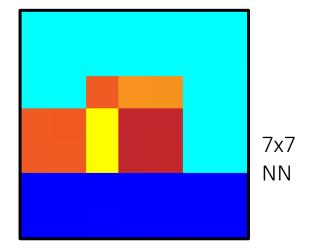




Bicubic



















Today's Agenda

- Image basics
 - What is an image addressing pixels
 - Image as a function image coordinates
- Image interpolation
 - Nearest neighbor
 - Bilinear
 - Bicubic
- Image resizing
 - Enlarge
 - Shrink





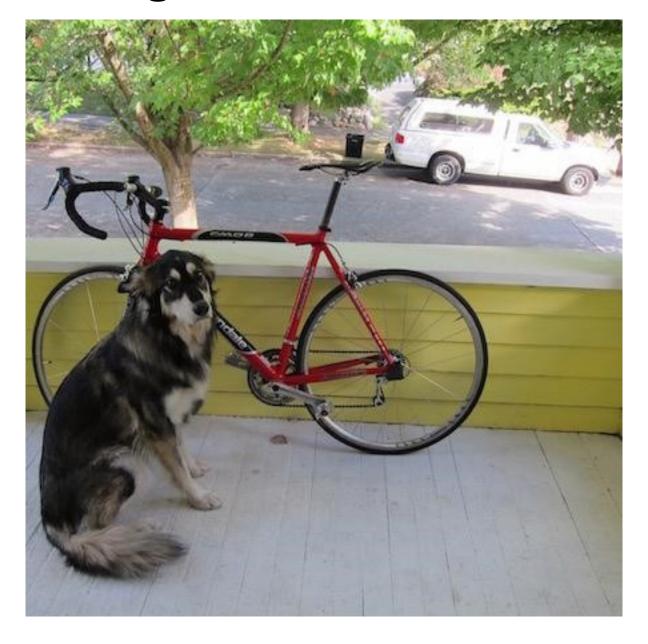








Want to make image smaller













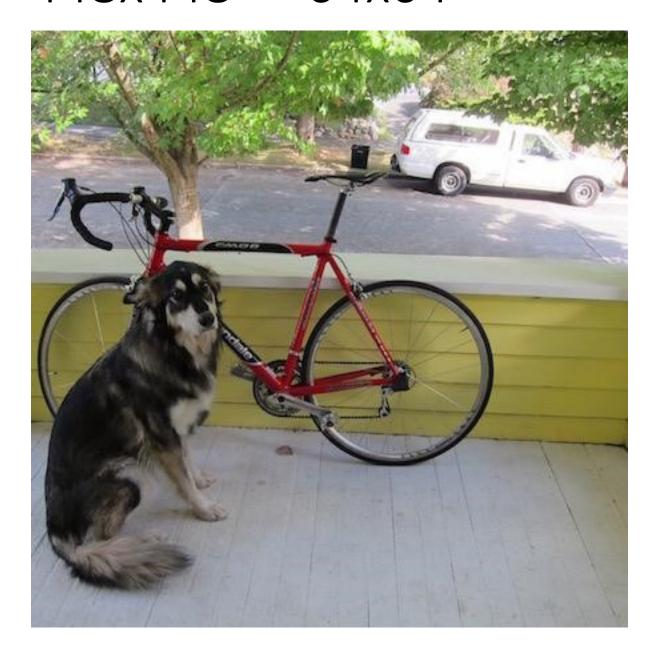














NN



Bilinear

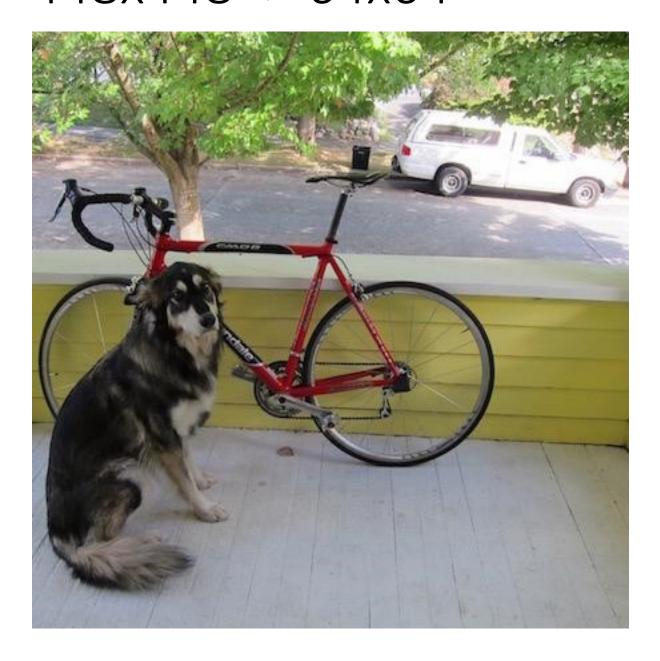
















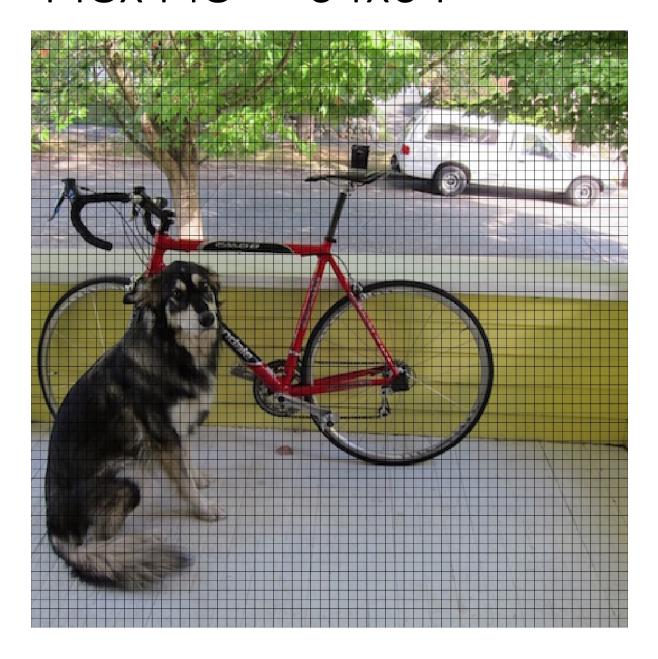














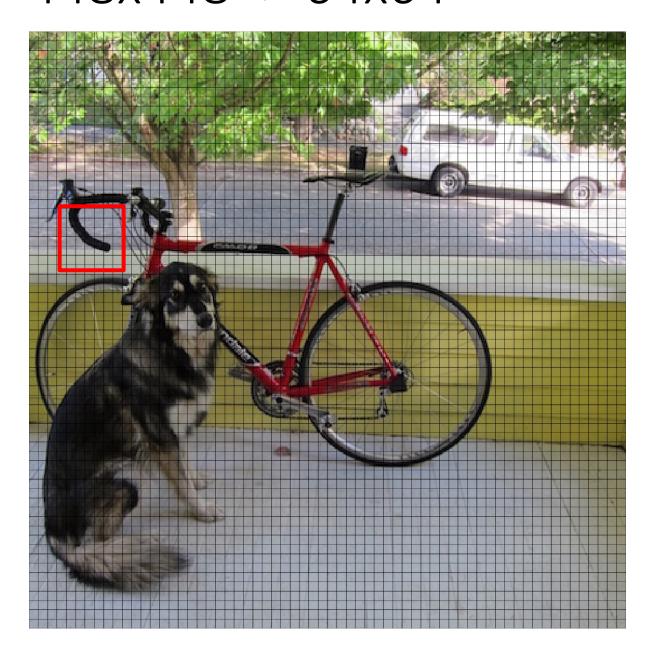


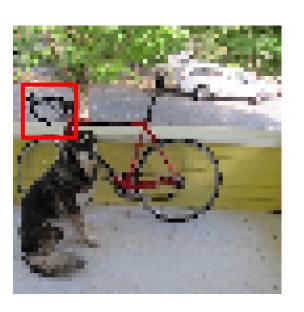










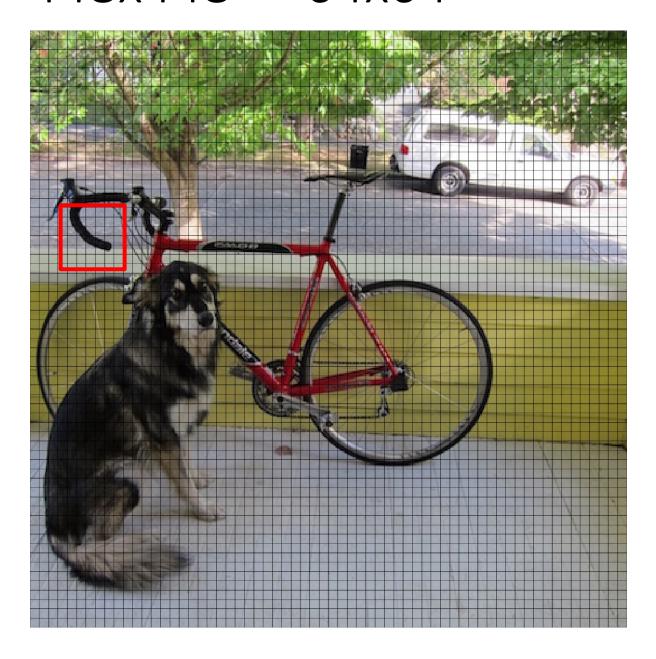


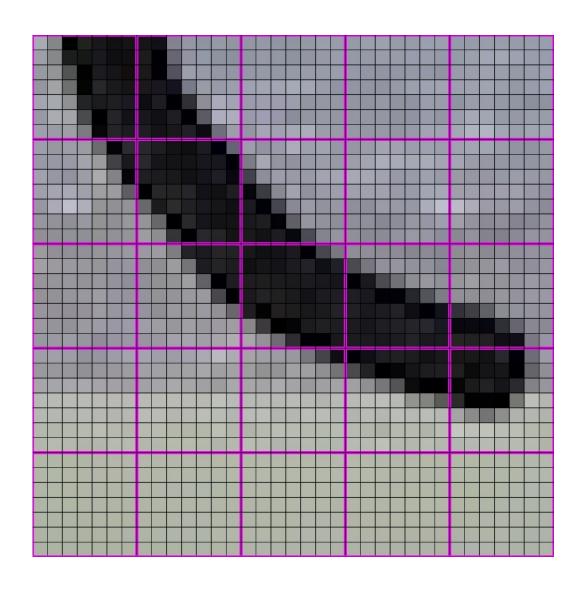










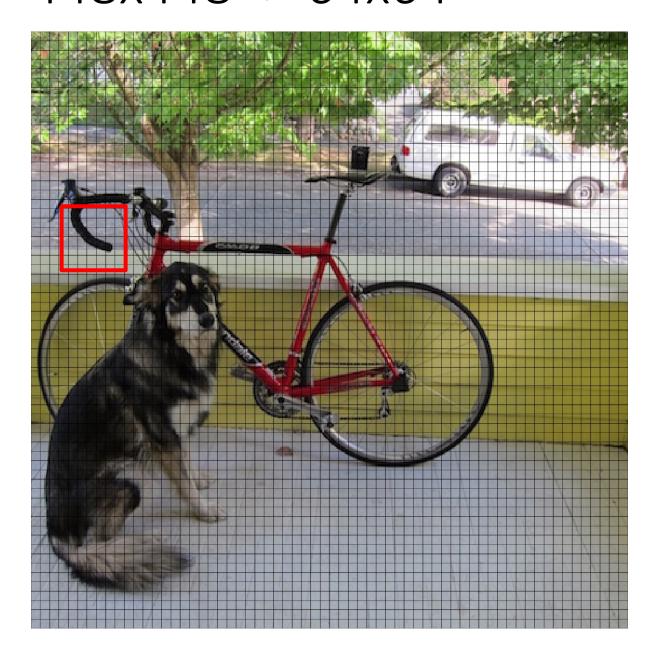


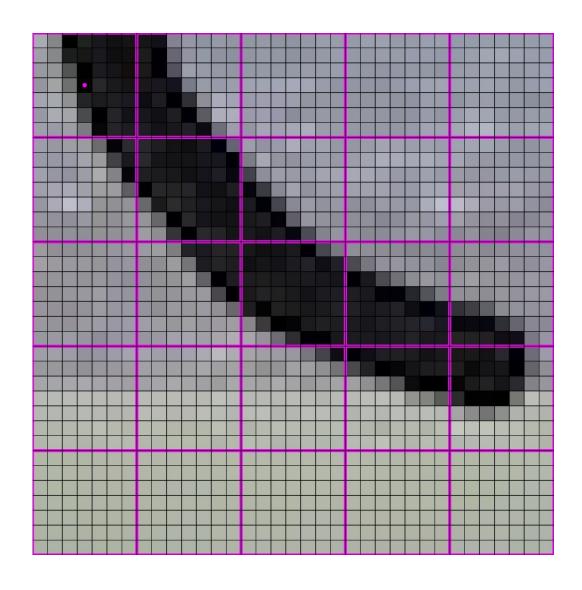










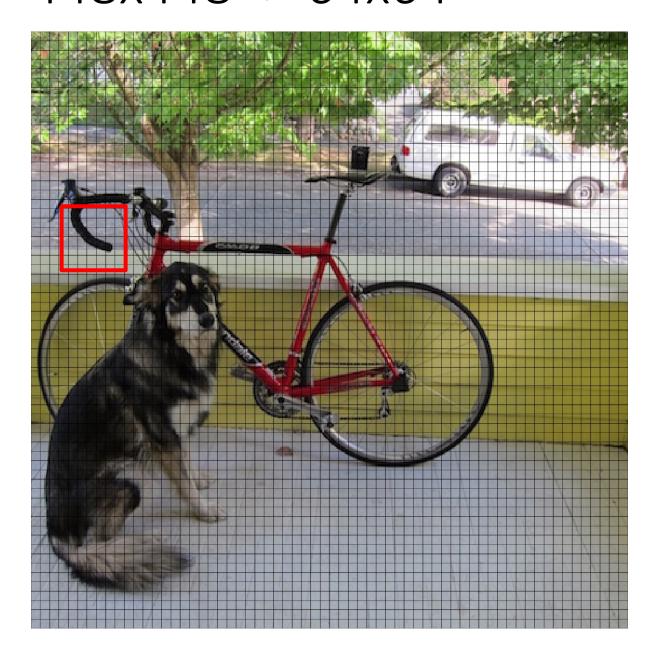


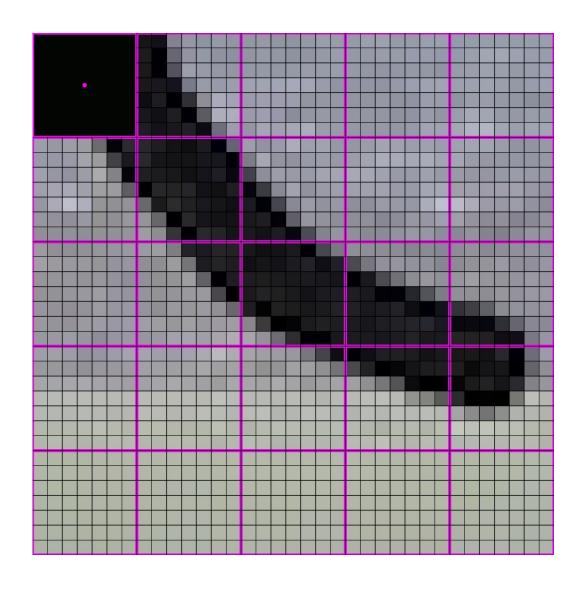










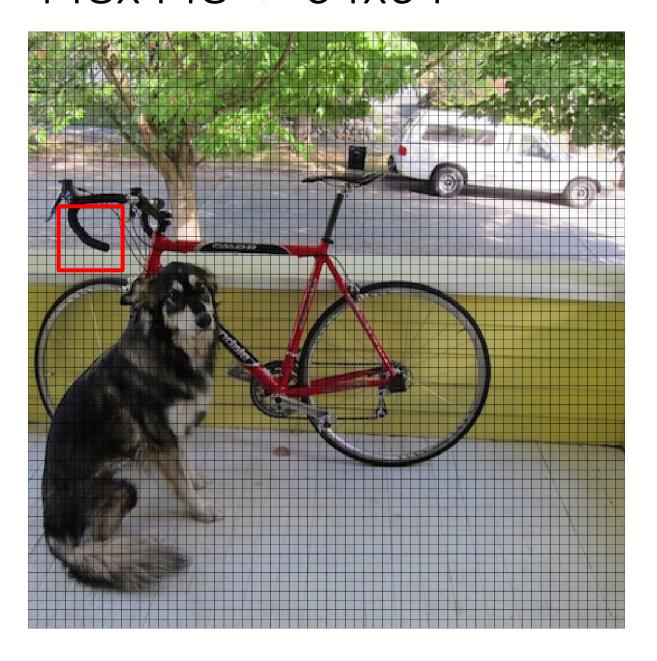


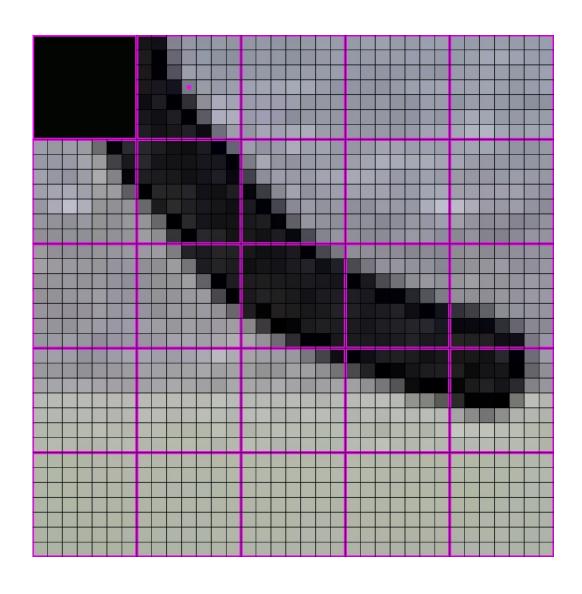










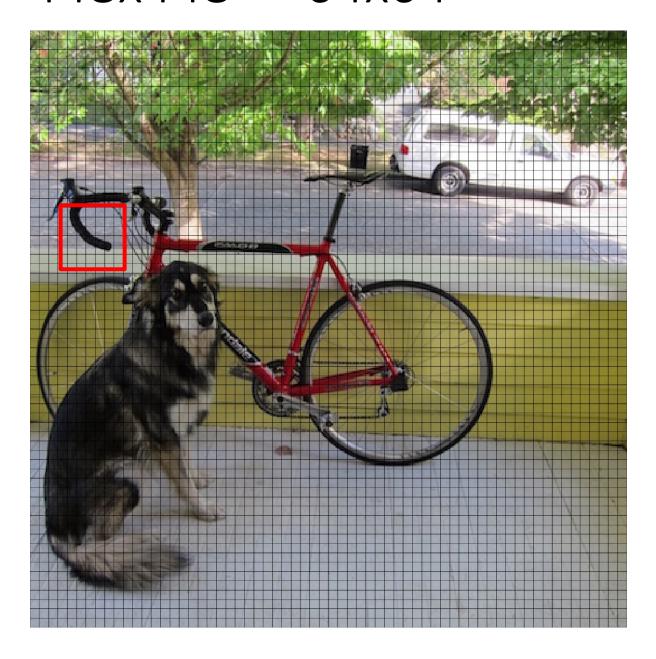


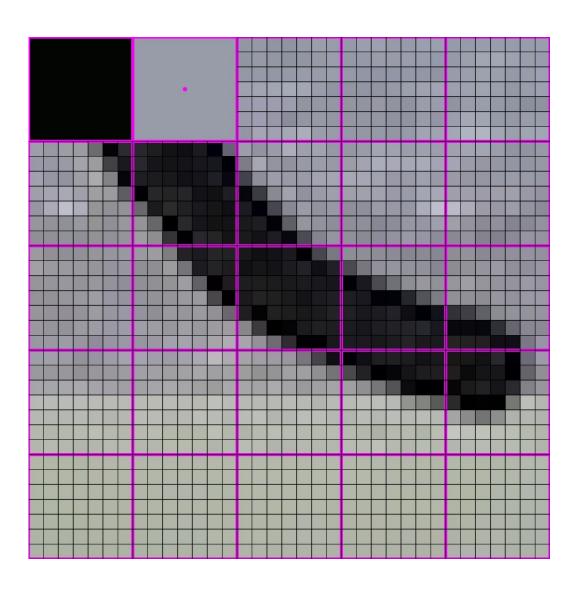












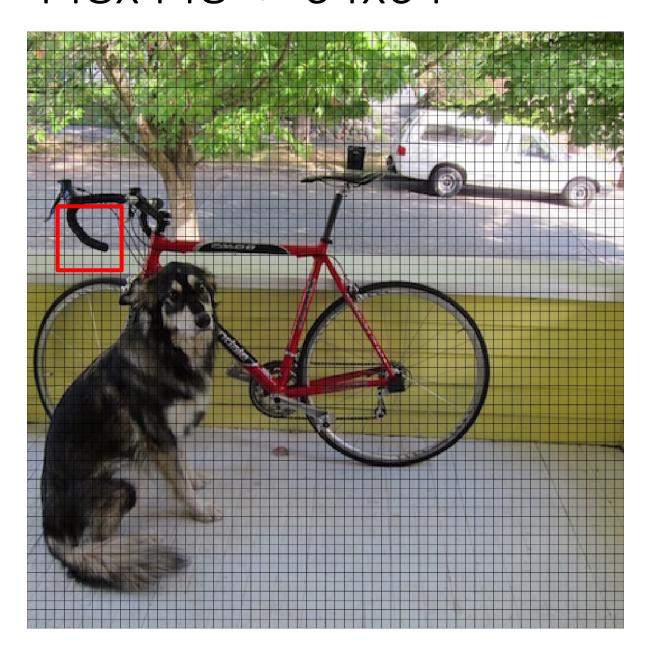


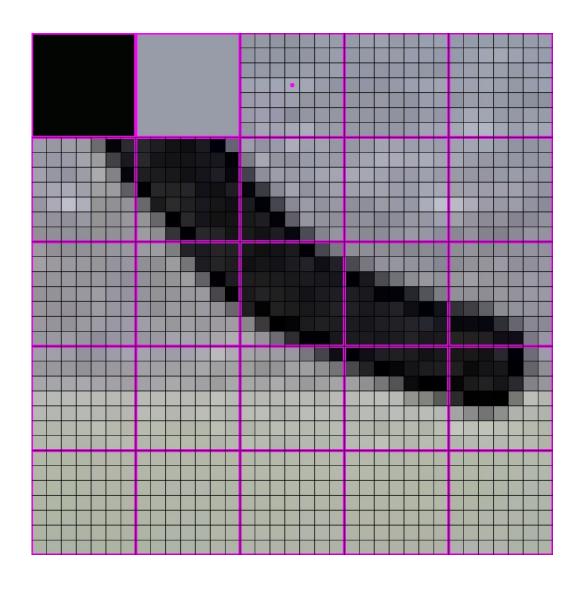










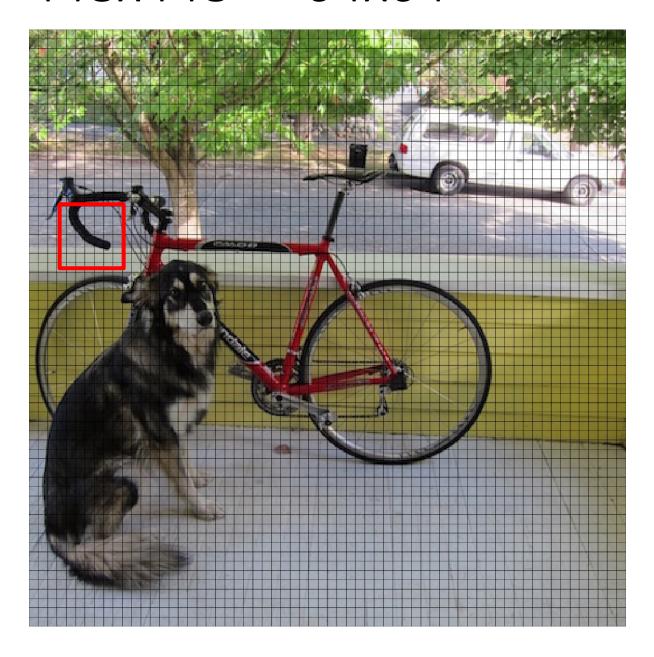


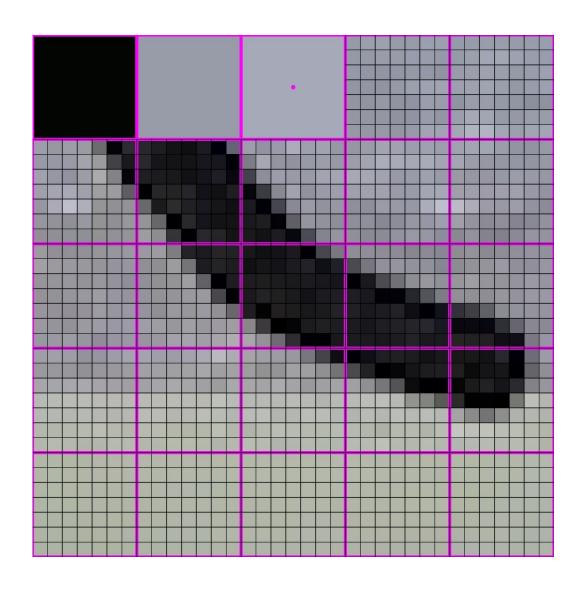










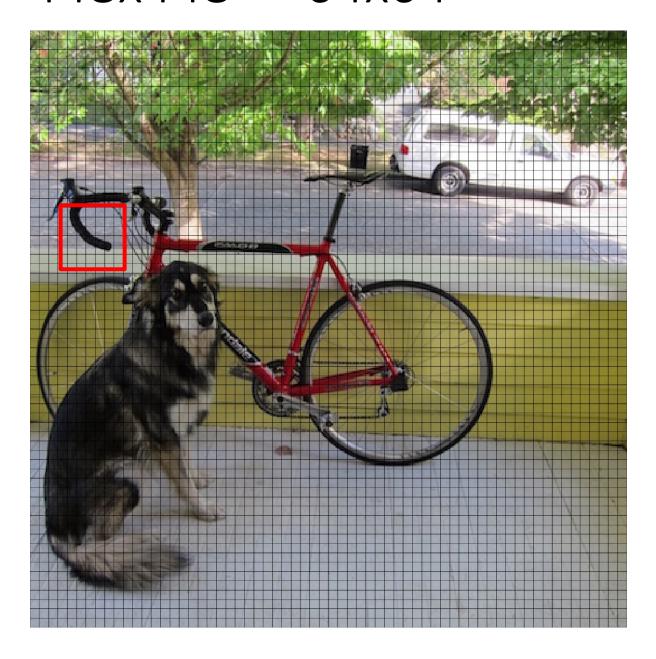


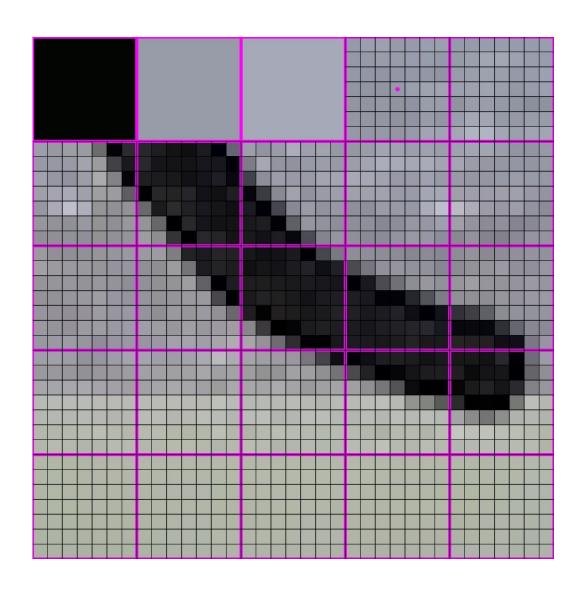










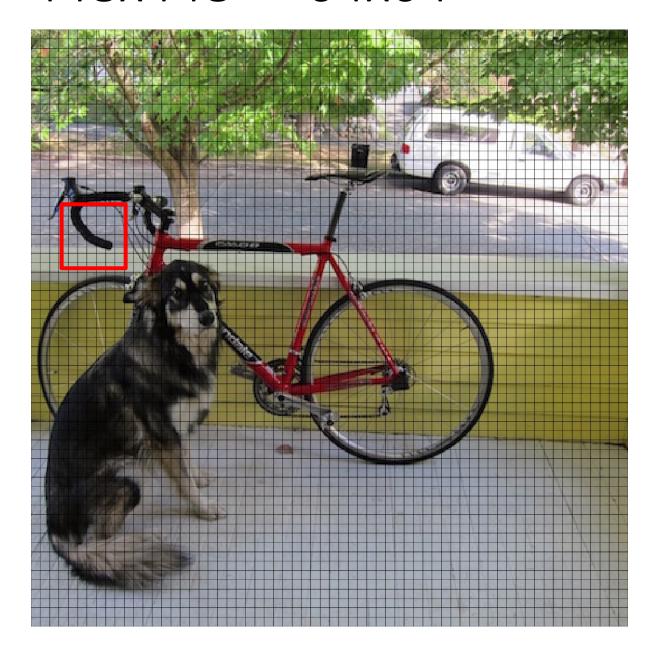


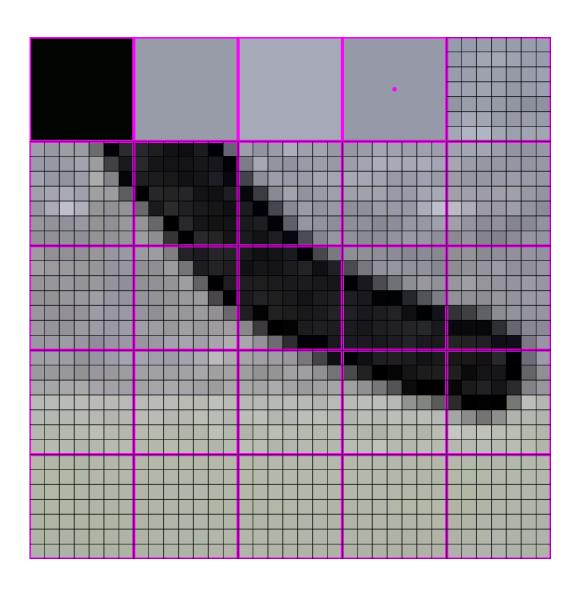












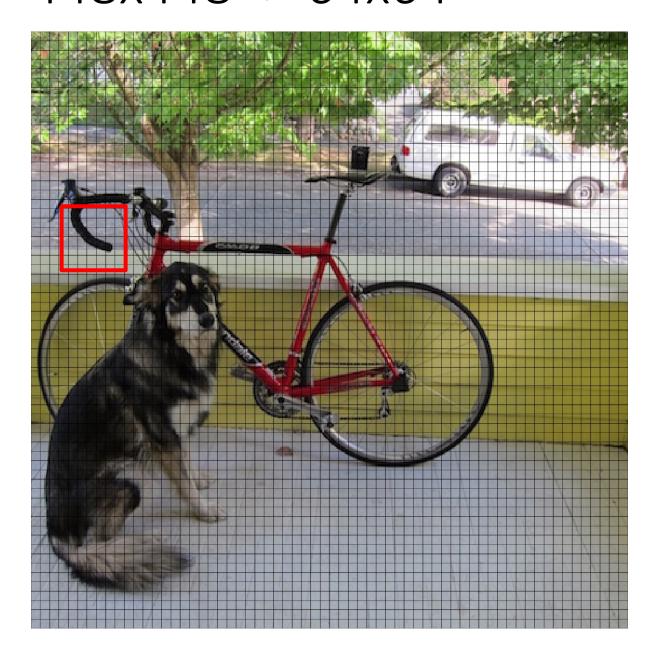


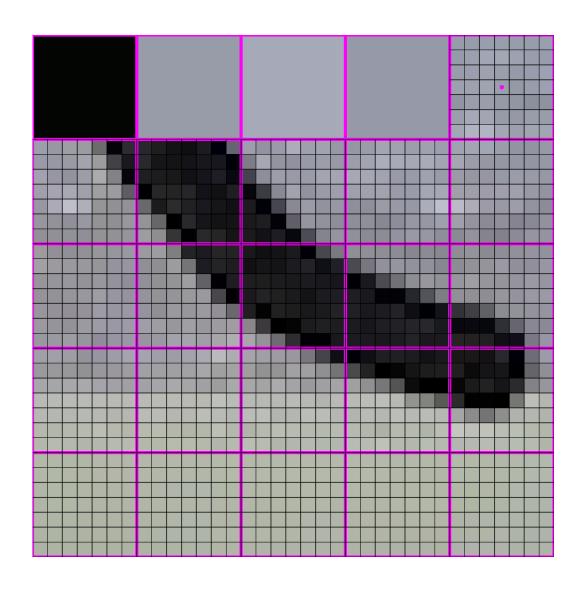










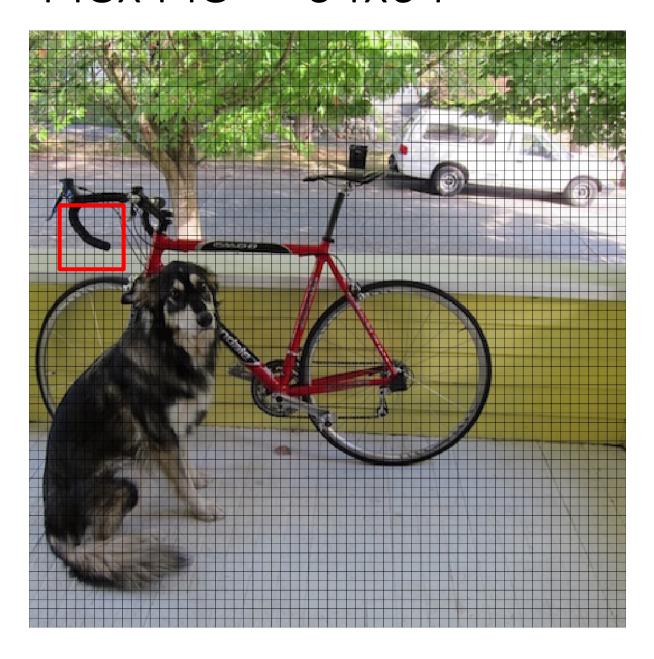


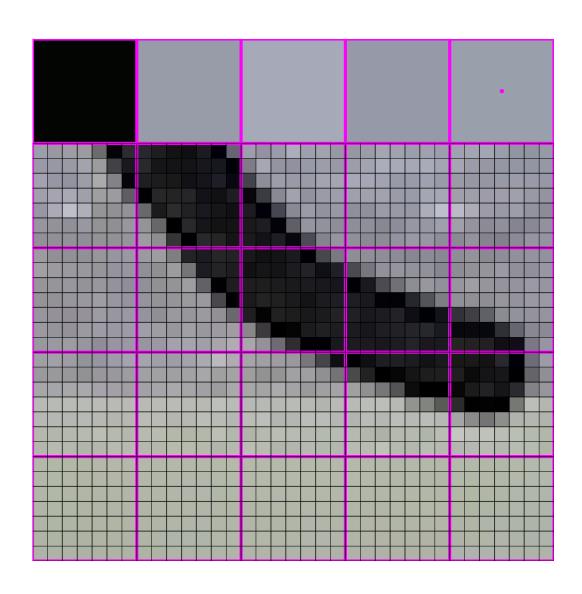










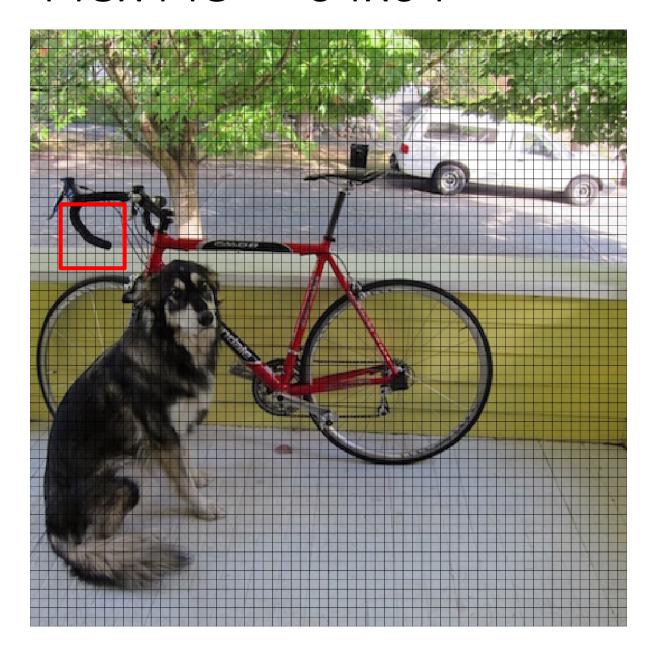


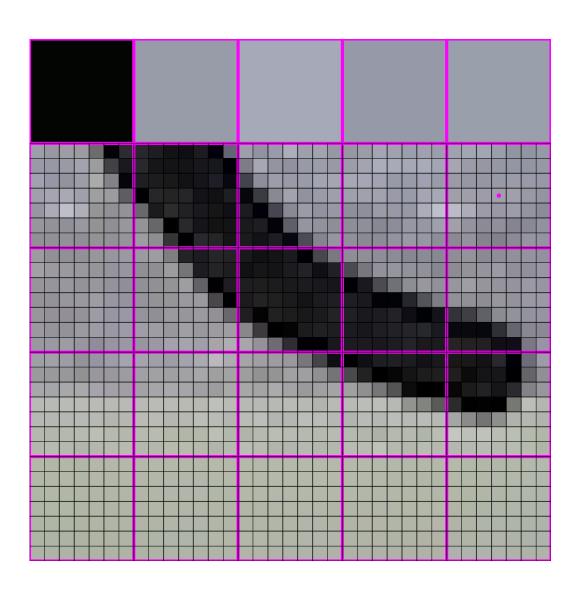












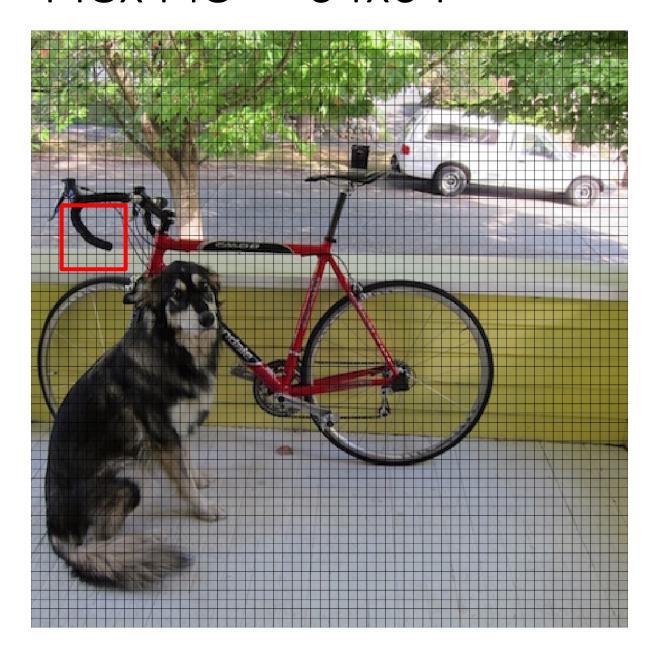


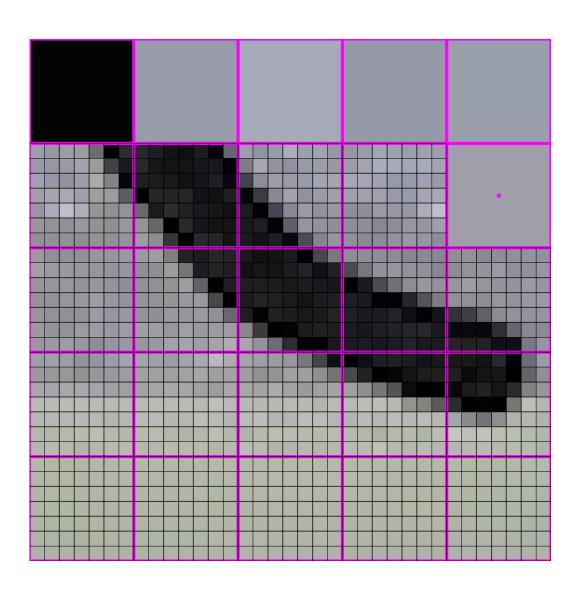












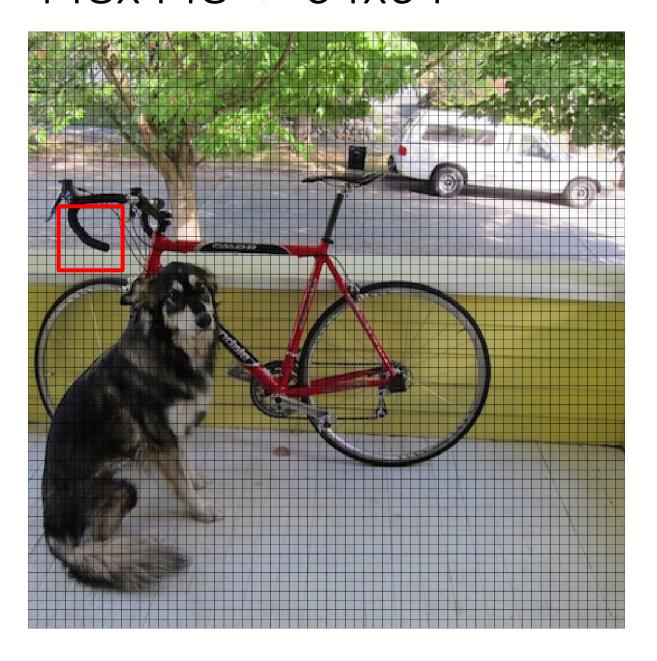


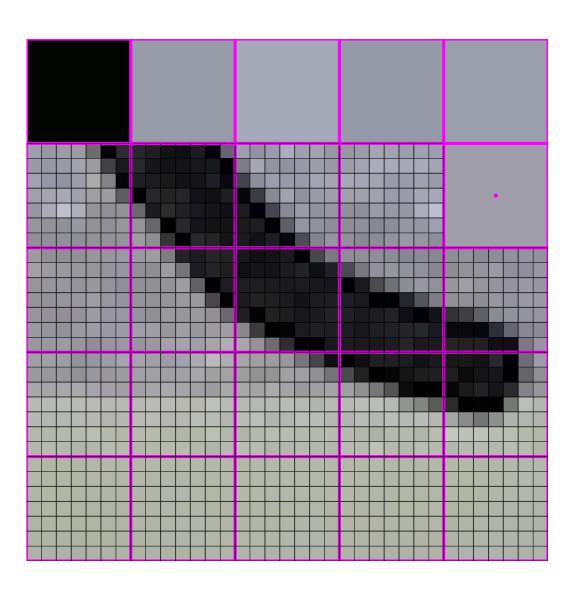










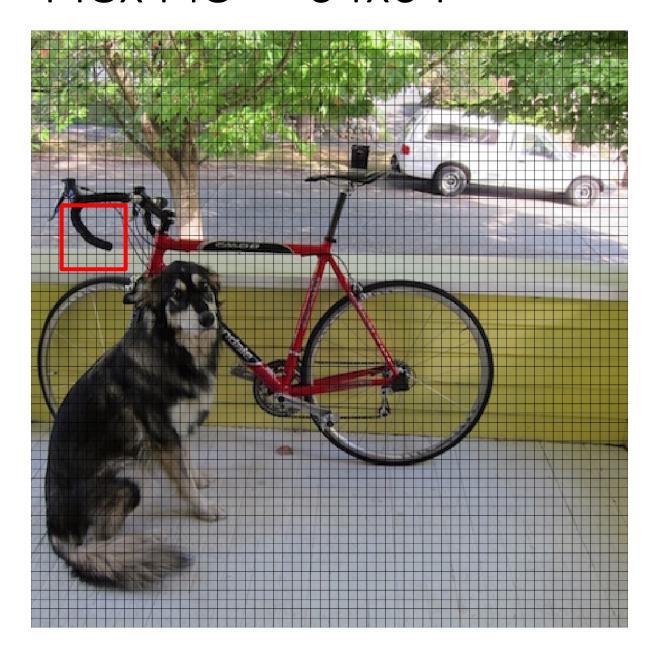


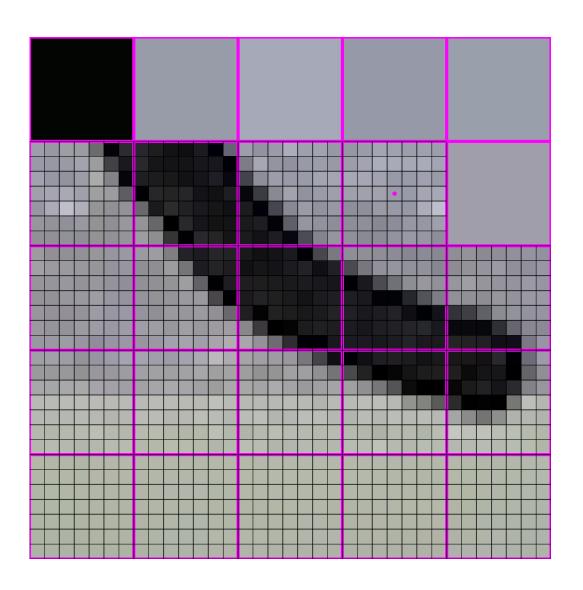












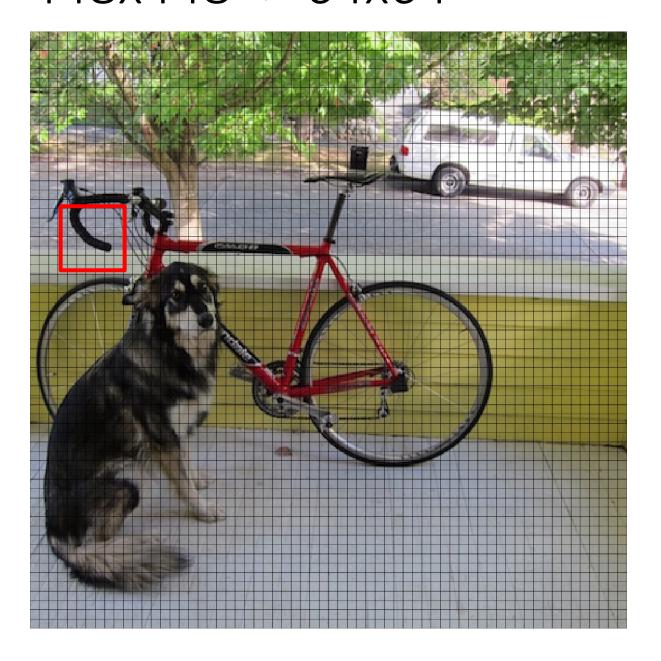


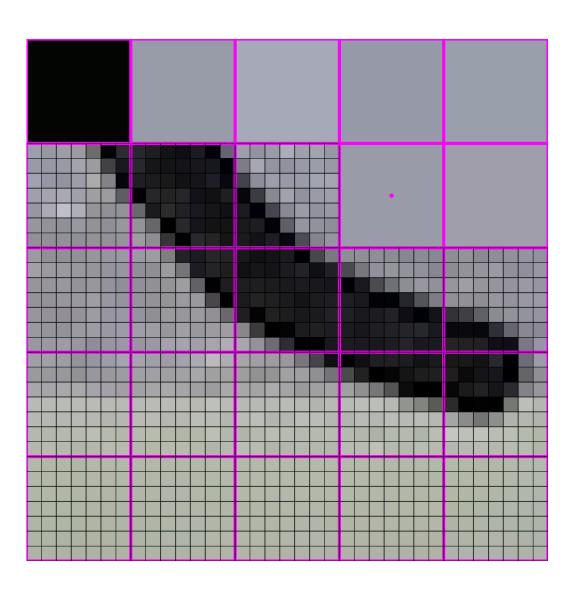










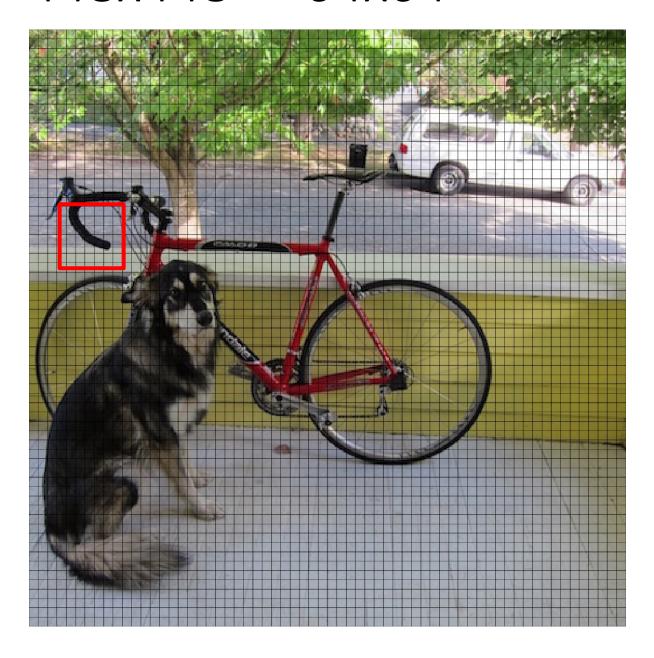


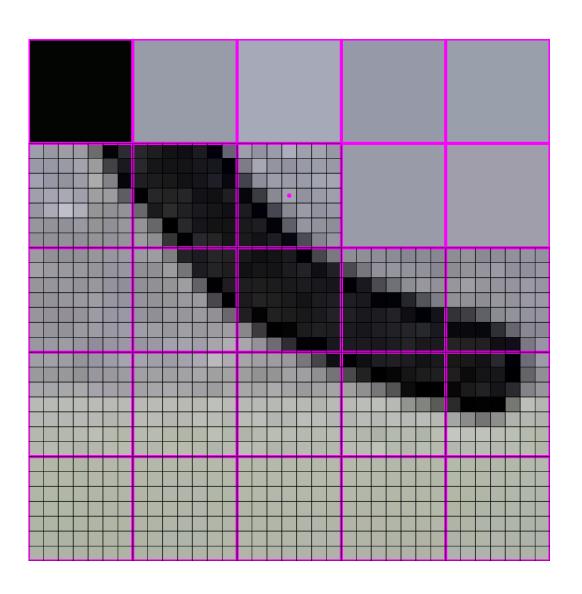








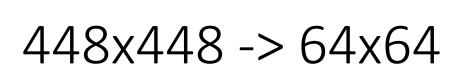


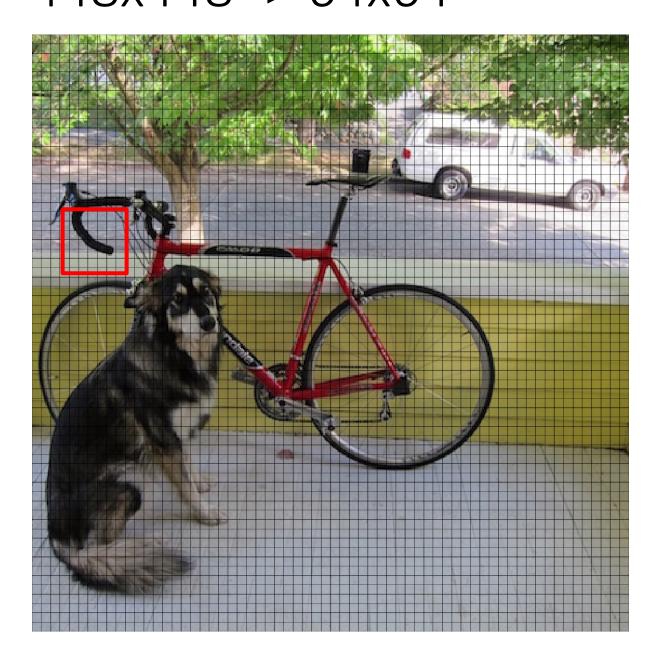


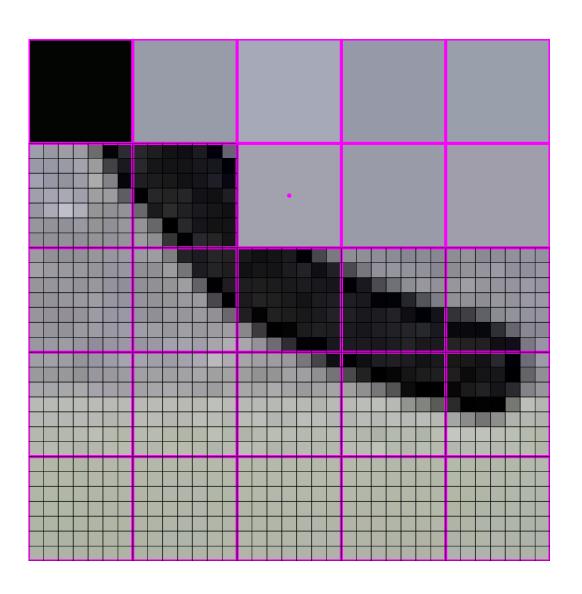










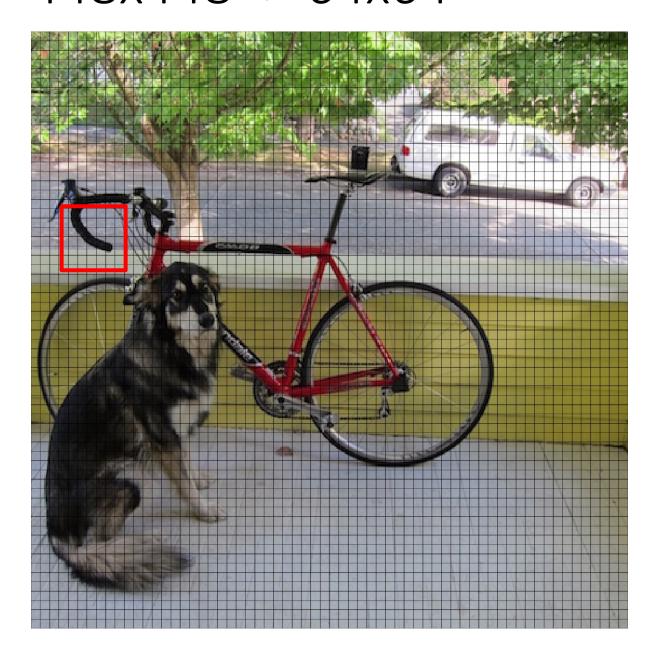


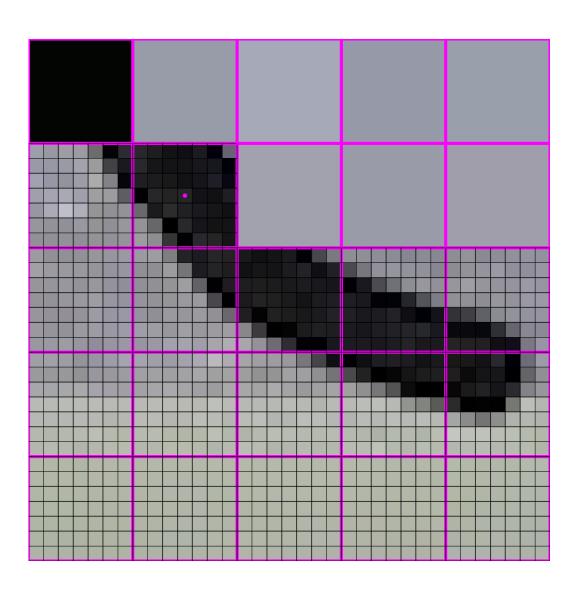










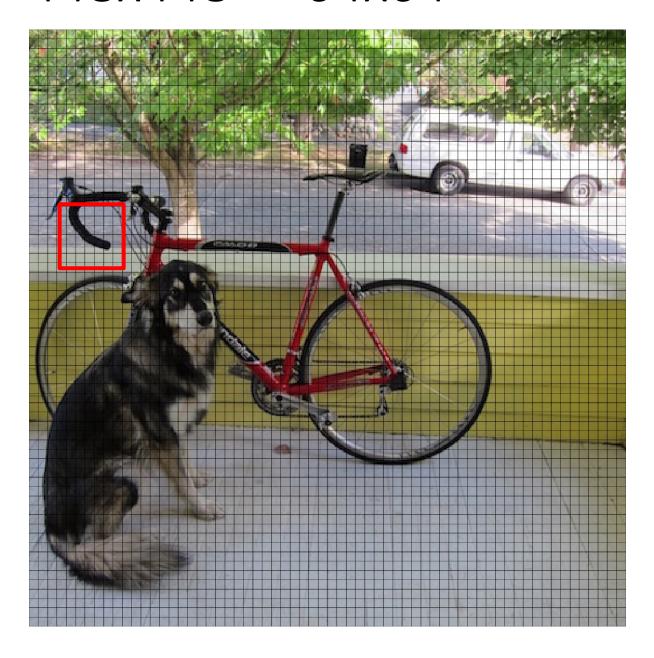


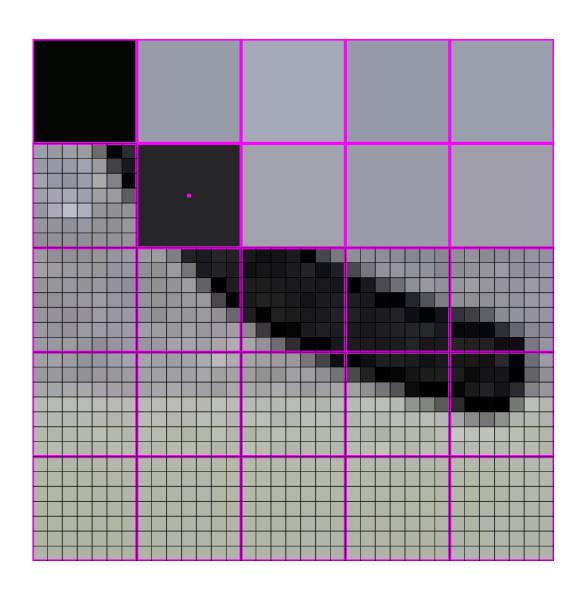










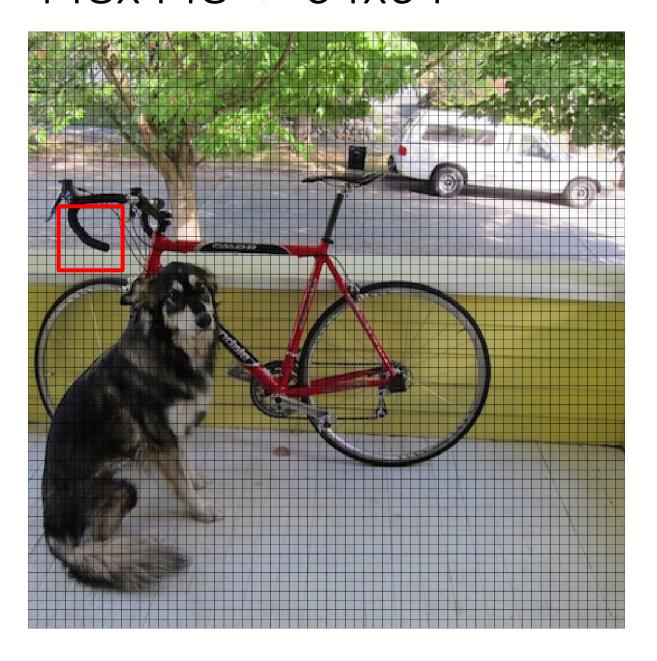


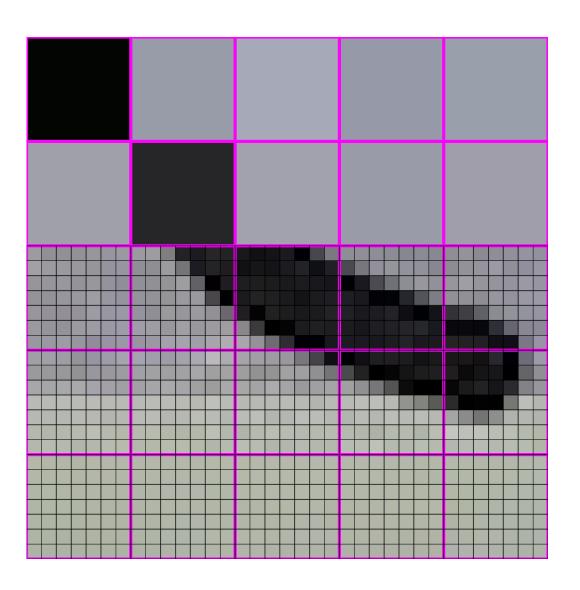












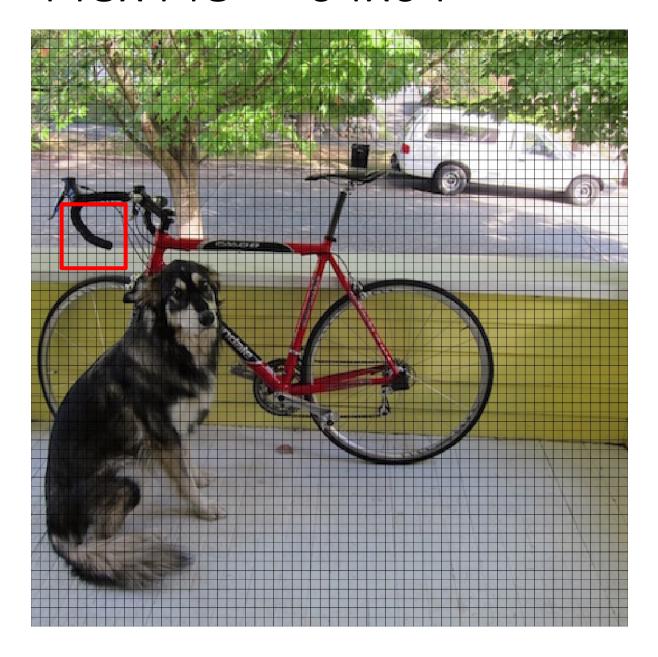


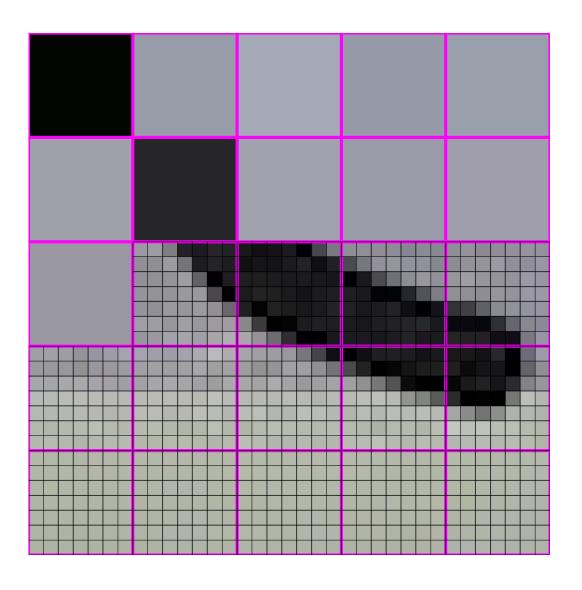










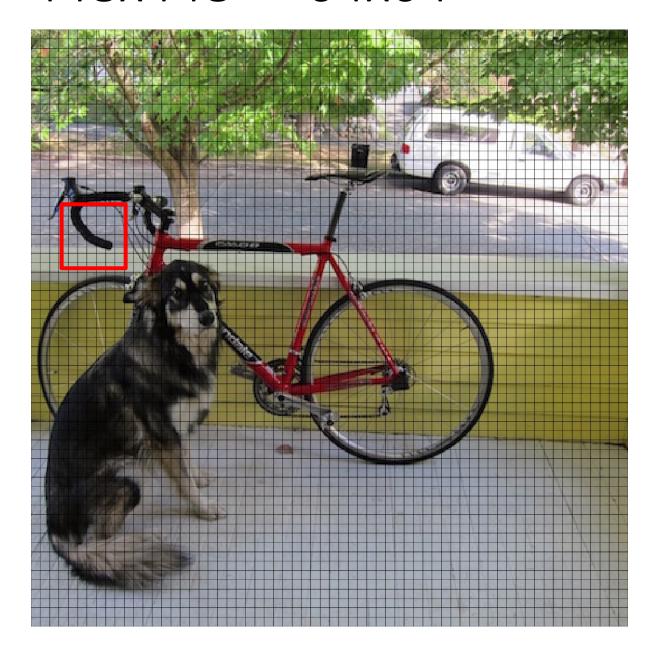


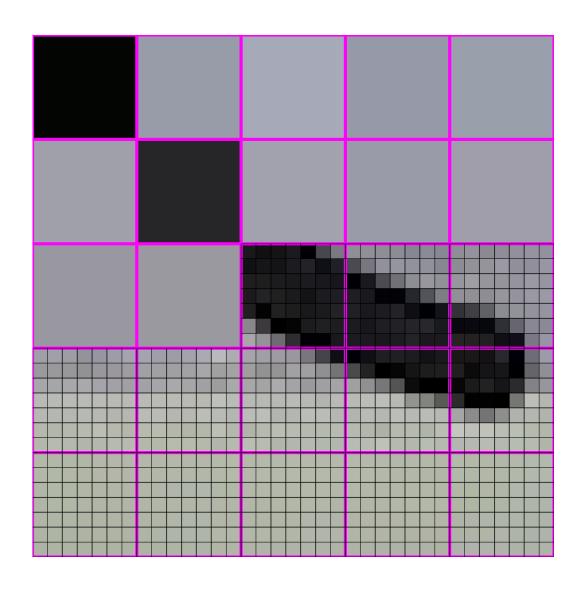








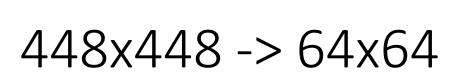


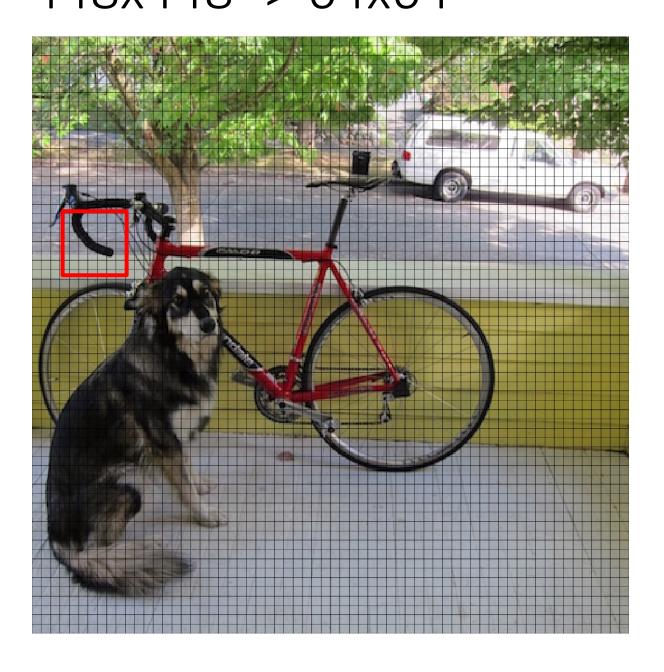


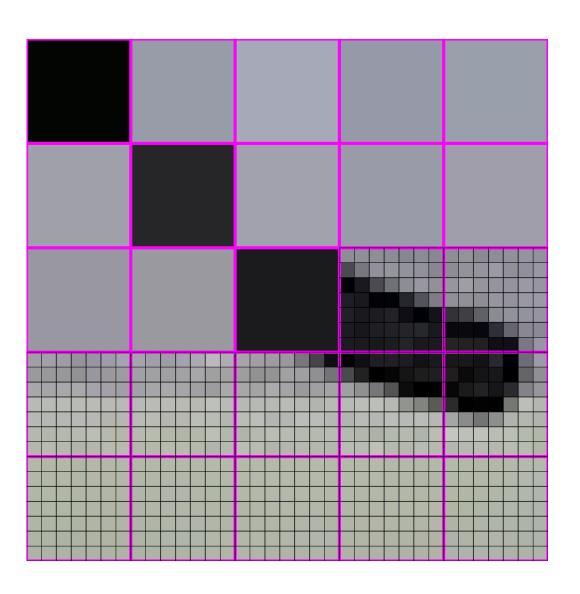








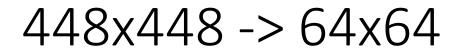


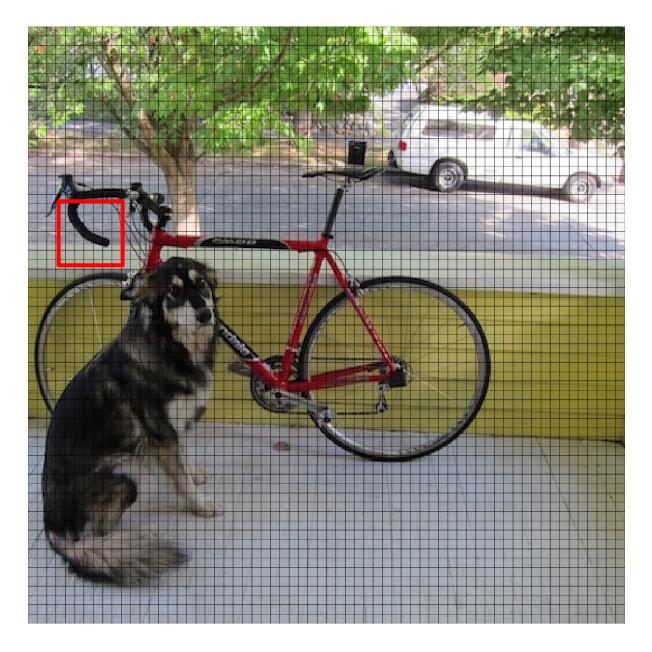


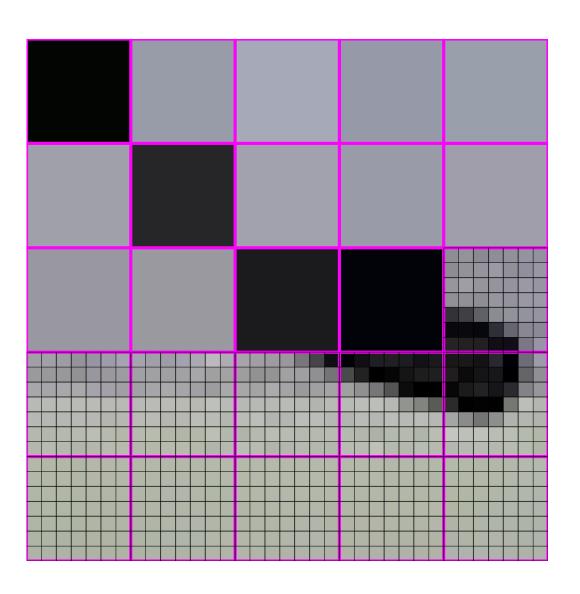














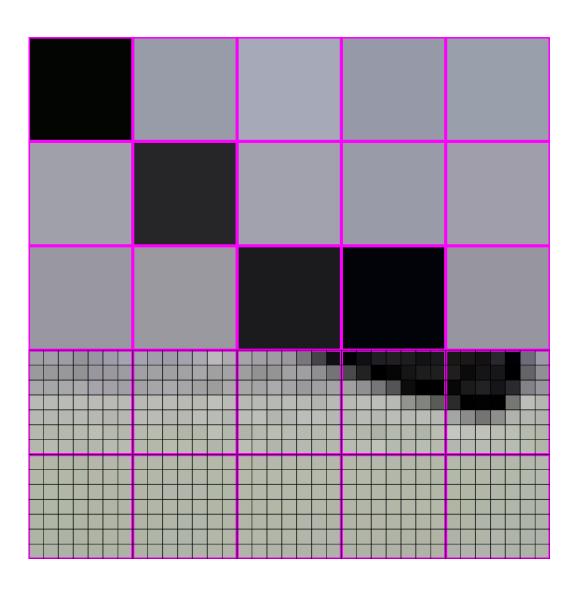












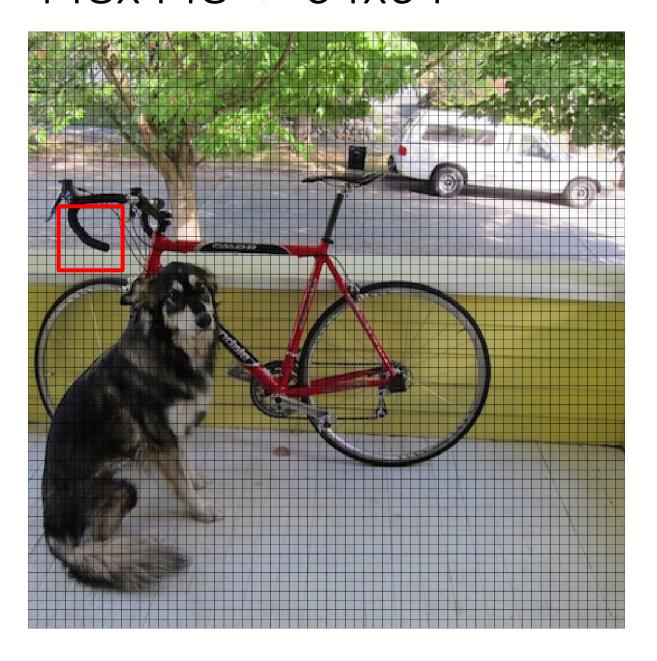


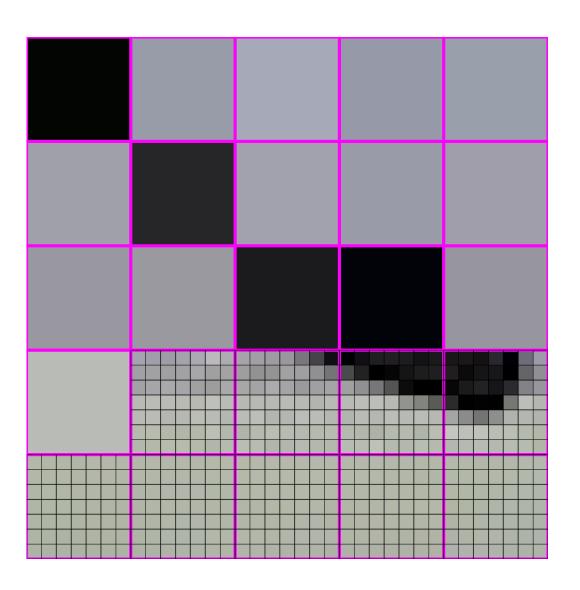












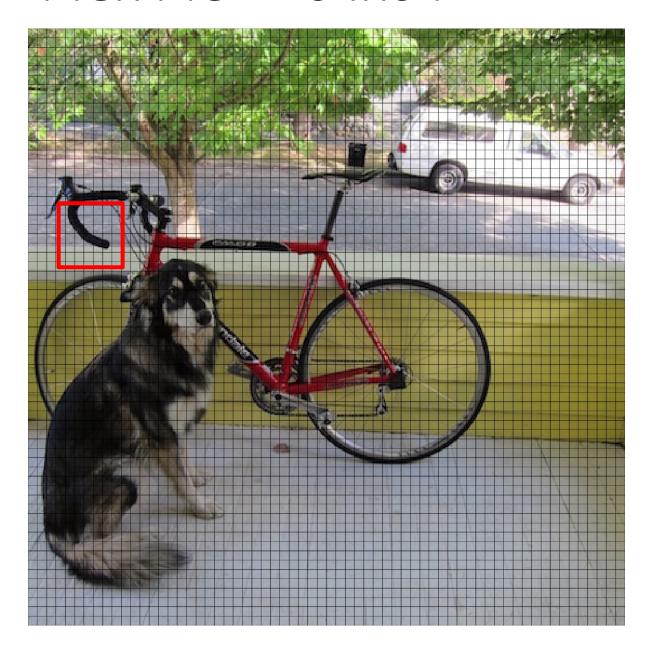


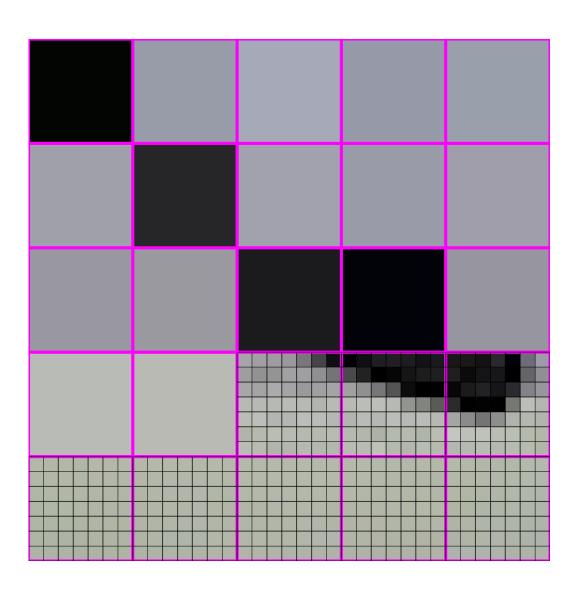












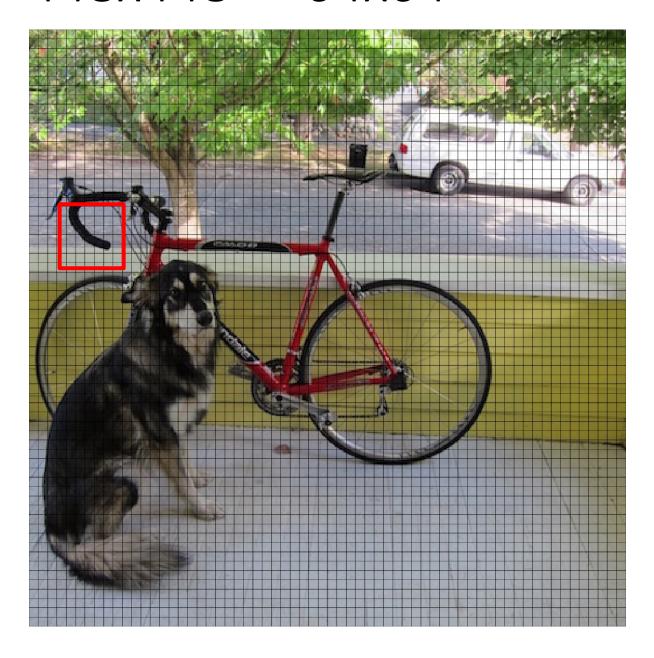


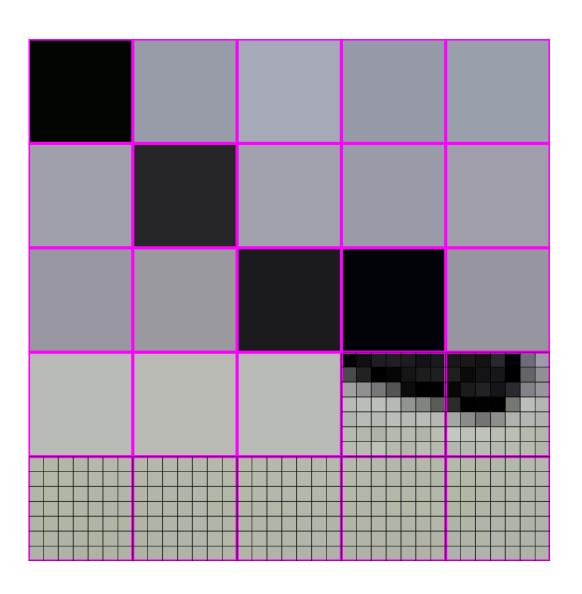










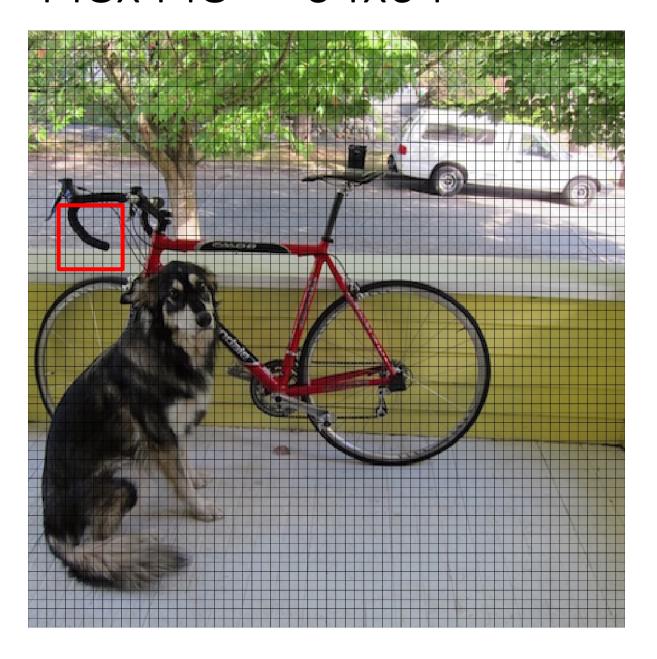


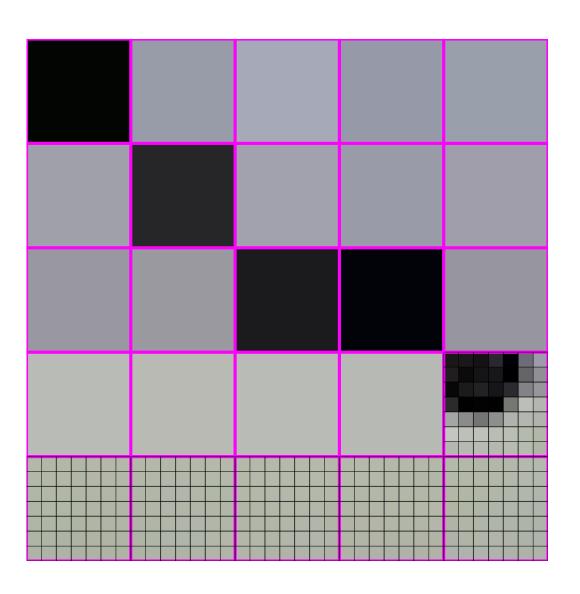








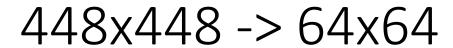


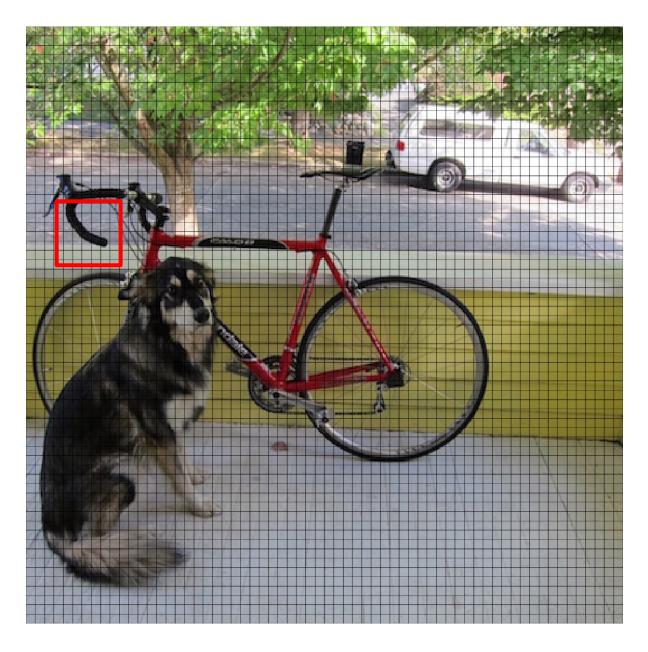


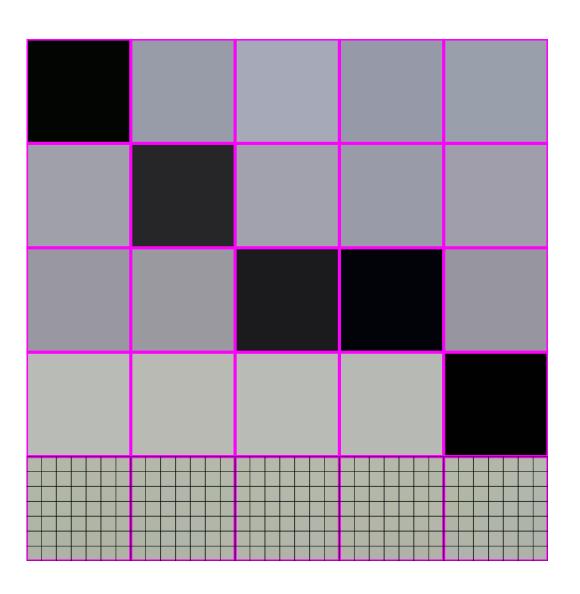








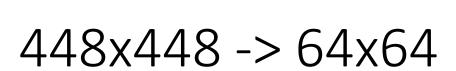


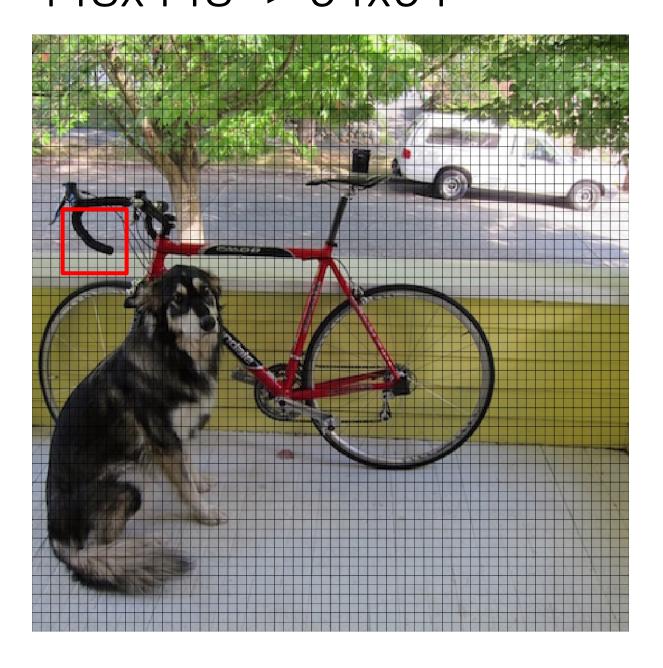


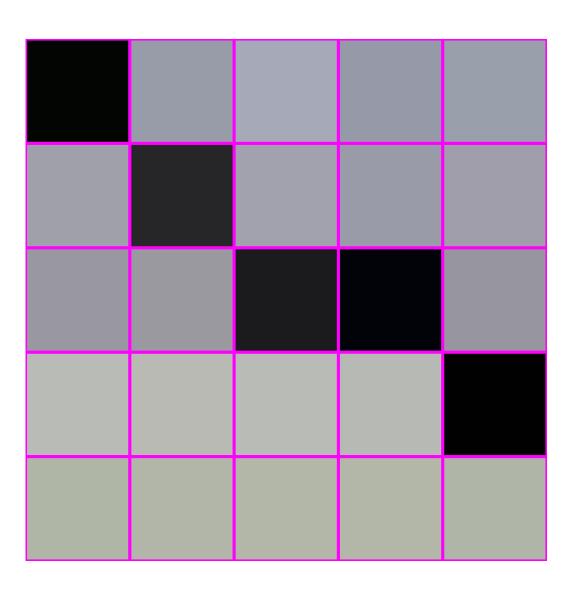












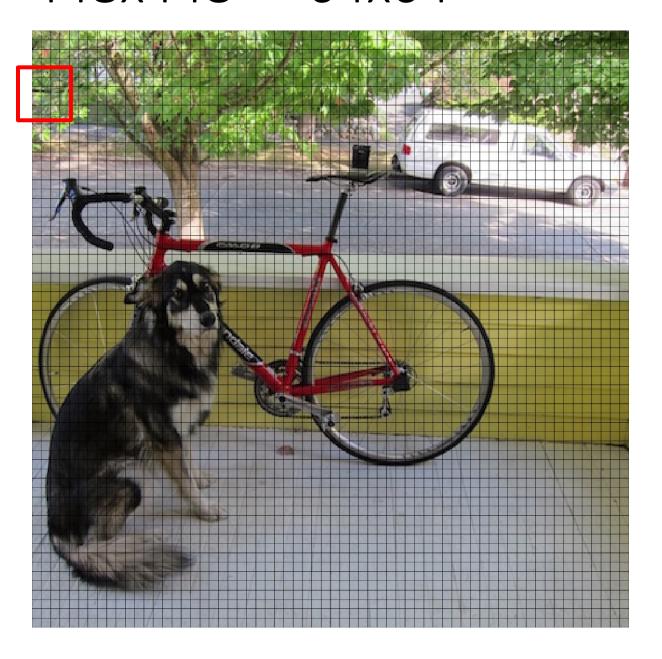


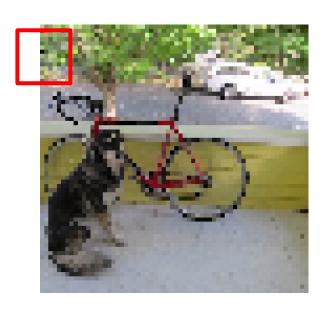










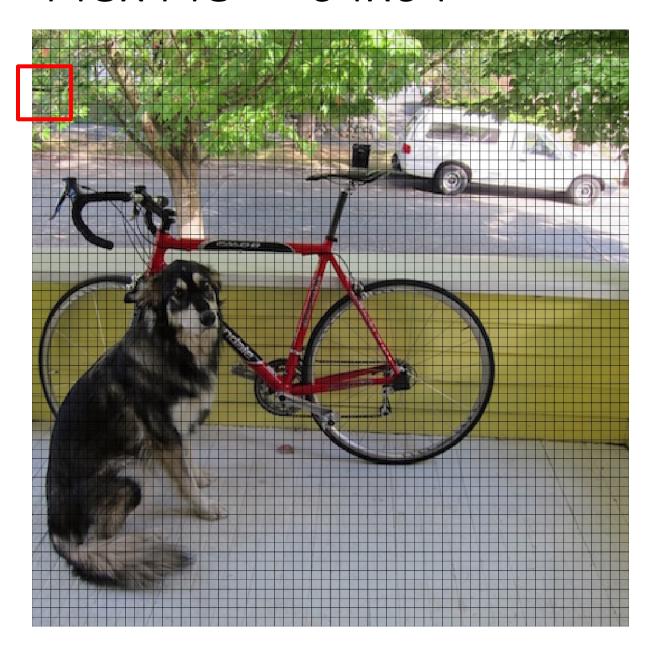


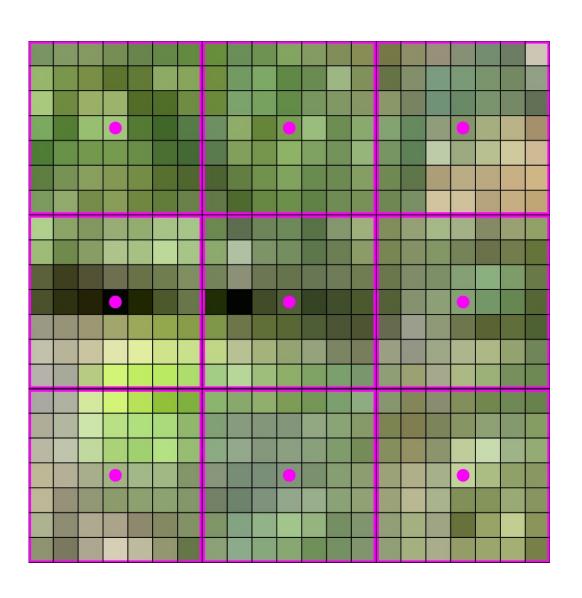












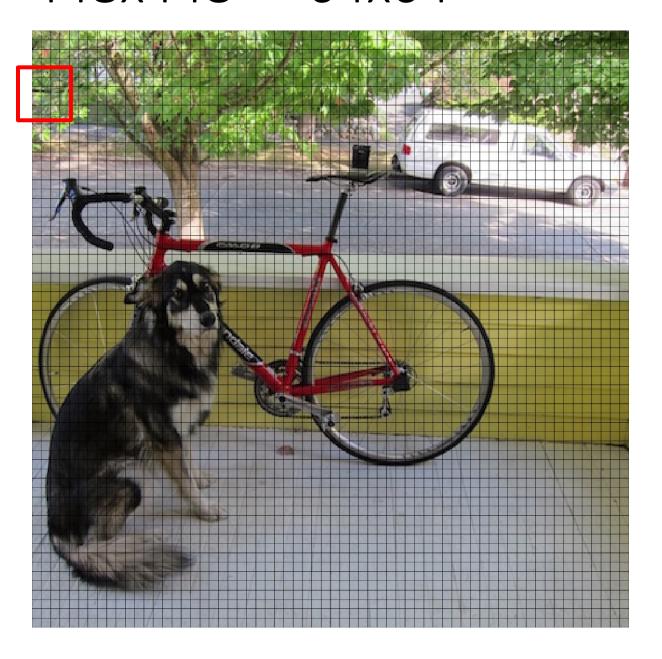


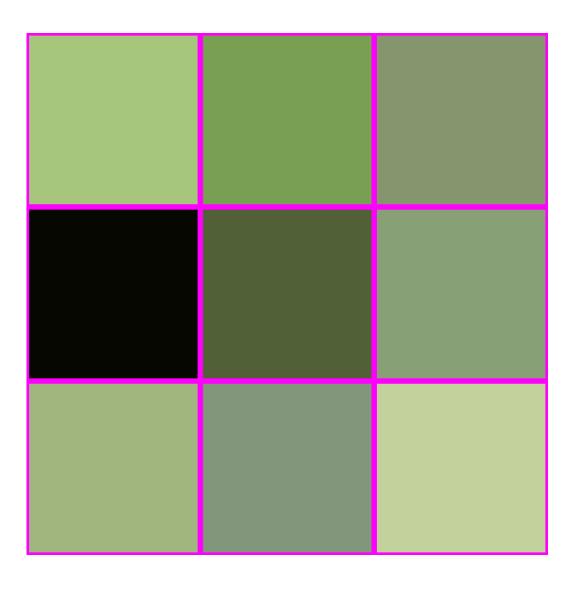




















Lots of issues

- NN and Bilinear only look at small area
- Lots of artifacting
- Staircase pattern on diagonal lines
- We'll fix this with filters!



NN



Bilinear











IS THIS ALL THERE IS??













THERE IS A BETTER WAY!











Thank you.



